Datasheet Version 2.1, 26 Oct 2007

# ICE2QS01

# Quasi-resonant PWM Controller

Power Management & Supply



Never stop thinking.

Downloaded from Elcodis.com electronic components distributor

#### ICE2QS01

Revision	History:	26 October 2007	Datasheet
Previous \	/ersion:	2.0	
Page	Subjects	(major changes since last revision)	
16	revised	outline dimension for PG-DIP-8 package(PCN nu	umber: PCN 2007-019-A)
	revised	disclaimer	

For questions on technology, delivery and prices please contact the Infineon Technologies Offices in Germany or the Infineon Technologies Companies and Representatives worldwide: see our webpage at http://www.infineon.com

CoolMOS<sup>™</sup>, CoolSET<sup>™</sup> are trademarks of Infineon Technologies AG.

Edition 2007-10-26

Published by Infineon Technologies AG 81726 Munich, Germany © 2007 Infineon Technologies AG All Rights Reserved.

#### Legal Disclaimer

The information given in this document shall in no event be regarded as a guarantee of conditions or characteristics. With respect to any examples or hints given herein, any typical values stated herein and/or any information regarding the application of the device, Infineon Technologies hereby disclaims any and all warranties and liabilities of any kind, including without limitation, warranties of non-infringement of intellectual property rights of any third party.

#### Information

For further information on technology, delivery terms and conditions and prices, please contact the nearest Infineon Technologies Office (<u>www.infineon.com</u>).

#### Warnings

Due to technical requirements, components may contain dangerous substances. For information on the types in question, please contact the nearest Infineon Technologies Office. Infineon Technologies components may be used in life-support devices or systems only with the express written approval of Infineon Technologies, if a failure of such components can reasonably be expected to cause the failure of that life-support device or system or to affect the safety or effectiveness of that device or system. Life support devices or systems are intended to be implanted in the human body or to support and/or maintain and sustain and/or protect human life. If they fail, it is reasonable to assume that the health of the user or other persons may be endangered.





# **Quasi-Resonant PWM Controller**

# **Product Highlights**

- · Active burst mode for low standby power
- Digital frequency reduction for better overall system efficiency
- · Integrated power cell for IC self-power supply

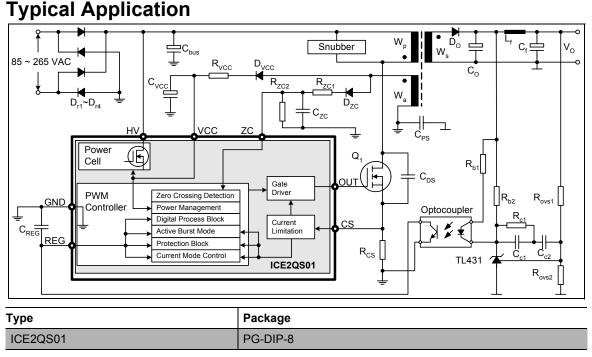


#### Features

- Quasiresonant operation till very low load
- Active burst mode operation at light load for low standby input power (< 1W)</li>
- · Digital frequency reduction with decreasing load
- Power cell for VCC pre-charging and IC power supply during latch-off, or standby mode operation when it is necessary
- Built-in digital soft-start
- Foldback correction and cycle-by-cycle peak current limitation
- Auto restart mode for VCC Overvoltage protection
- Auto restart mode for VCC Undervoltage protection
- Auto restart mode for openloop/overload protection
  Latch-off mode for adjustable output overvoltage
- protection
- Latch-off mode for Short-winding protection

#### Description

ICE2QS01 is a quasi-resonant PWM controller optimized for off-line switch power supply applications such as LCD TV, CRT TV and notebook adapter. The digital frequency reduction with decreasing load enables a quasi-resonant operation till very low load. As a result, the system efficiency is significantly improved compared to other conventional solutions. The active burst mode operation enables an ultra-low power consumption at standby mode with small and controllable output voltage ripple. The innovative power cell solves the IC power supply problem when the output voltage is pulled down during standby mode, or during latch-off mode. The numerous protection functions give a full protection of the power supply system in failure situations. All of these make the ICE2QS01 an outstanding controller for quasiresonant flyback converter in the market.



#### Version 2.1



Table of	Contents F	Page
<b>1</b> 1.1 1.2 1.3	Pin Configuration and FunctionalityPin ConfigurationPackage PG-DIP-8Pin Functionality	5 5
2	Representative Block Diagram	6
<b>3</b> 3.1 3.2 3.3 3.3.1 3.3.2 3.3.3 3.4 3.4.1 3.4.2 3.4.3 3.4.4 3.5	Functional Description.VCC Pre-Charging and Typical VCC Voltage During Start-upSoft-startNormal OperationSwitch-on Determination.Switch-off Determination.Foldback Point CorrectionActive Burst Mode OperationEntering Active Burst Mode OperationDuring Active Burst Mode OperationLeaving Active Burst Mode OperationIC Power Supply During Active Burst Mode OperationProtection Functions	7 7 7 9 10 10 10 10 10 10 10
<b>4</b> 4.1 4.2 4.3 4.3.1 4.3.2 4.3.3 4.3.4	Electrical Characteristics. Absolute Maximum Ratings Operating Range Characteristics Supply Section PWM Section Protection Gate Driver	12 12 13 13 13 14 15
5	Outline Dimension	16



# Quasi-Resonant PWM Controller ICE2QS01

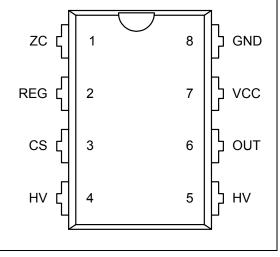
## **Pin Configuration and Functionality**

# **1** Pin Configuration and Functionality

## 1.1 Pin Configuration

Pin	Symbol	Function
1	ZC	Zero Crossing
2	REG	Regulation
3	CS	Primary Current Sensing
4, 5	HV	High Voltage input
6	OUT	gate driver <b>out</b> put
7	VCC	IC supply voltage
8	GND	Common ground

## 1.2 Package PG-DIP-8





Pin Configuration PG-DIP-8(top view)

## 1.3 Pin Functionality

#### ZC (Zero Crossing)

At this pin, the voltage from the auxiliary winding after a time delay circuit is applied. Internally, this pin is connected to the zero-crossing detector for switch-on determination. Additionally, the output overvoltage detection is realized by comparing the voltage  $V_{zc}$  with an internal preset threshold.

#### REG (Regulation)

Normally, an external capacitor is connected to this pin for a smooth voltage  $V_{reg}$ . Internally, this pin is connected to the PWM signal generator for switch-off determination (together with the current sensing signal), the digital signal processing for the frequency reduction with decreasing load during normal operation, and the burst mode controller for entering burst mode operation determination and burst ratio control during burst mode operation. Additionally, the open-loop / over-load protection is implemented by monitoring the voltage at this pin.

#### CS (Current Sensing)

This pin is connected to the shunt resistor for the primary current sensing, externally, and the PWM signal generator for switch-off determination (together with the regulation voltage), internally. Moreover, shortwinding protection is realised by monitoring the voltage  $V_{cs}$  during on-time of the main power switch.

#### HV (High Voltage)

The pin HV is connected to the bus voltage, externally, and to the power cell, internally. The current through this pin pre-charges the VCC capacitor once the supply bus voltage is applied. Additionally, the current through this pin supplies the IC in case that the output voltage is lowered during active burst mode operation, or during latch-off mode.

#### **OUT** (Gate drive output)

This output signal drives the external main power switch, which is a power MOSFET in most case.

#### VCC (Power supply)

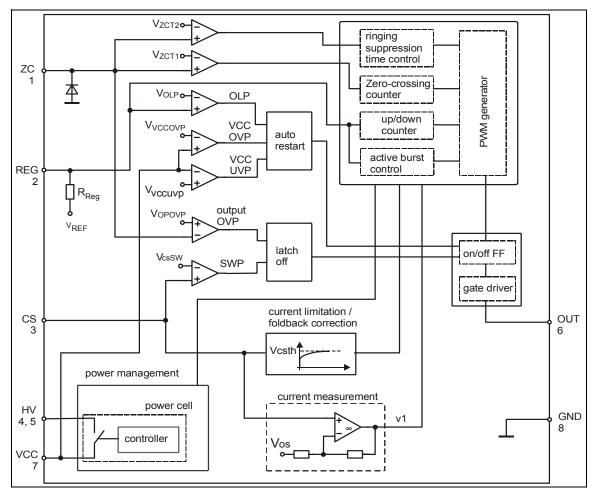
This is the IC power supply pin. Externally, this pin is connected to the VCC capacitor, which is supplied by the inside power cell during VCC charge-up, burst mode operation at lowered output voltage or during latched-off of the IC, and the auxiliary winding during normal operation or burst mode operation with high enough voltage across the auxiliary winding. Based on this voltage, the VCC under- or over-voltage protection are implemented.

#### GND (Ground)

This is the common ground of the controller.



# Representative block diagram



# 2 Representative block diagram

Figure 2 Representative Blockdigram



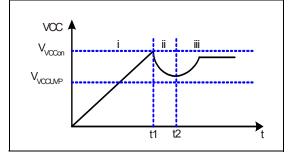
#### **Functional Description**

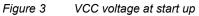
# **3** Functional Description

# 3.1 VCC Pre-Charging and Typical VCC Voltage During Start-up

In the controller ICE2QS01, a power cell is integrated. As shown in Figure 2, the power cell consists of a high voltage device and a controller, whereby the high voltage device is controlled by the controller. The power cell provides a pre-charging of the VCC capacitor till VCC voltage reaches the VCC turned-on threshold  $V_{VCCon}$  and the IC begins to operate, while it may keep the VCC voltage at a constant value during burst mode operation when the output voltage is pulled down or the power from the auxiliary winding is not enough, or when the IC is latched off in certain protection mode.

Once the mains input voltage is applied, a rectified voltage shows across the capacitor  $C_{\rm bus}$ . The high voltage device provides a current to charge the VCC capacitor  $C_{\rm vcc}$ . Before the VCC voltage reaches a certain value, the amplitude of the current through the high voltage device is only determined by its channel resistance and can be as high as several mA. After the VCC voltage device so that a constant current around 1mA is provided to charge the VCC capacitor further, until the VCC voltage exceeds the turned-on threshold  $V_{\rm VCCon}$ . As shown as the time phase I in Figure 3, the VCC voltage increase near linearly.





The time taking for the VCC pre-charging can then be approximately calculated as:

$$t_1 = \frac{V_{VCCon} \cdot C_{vcc}}{I_{VCCcharge2}}$$
[1]

where  $I_{\rm VCCcharge2}$  is the charging current from the power cell which is 1.05mA, typically.

Exceeds the VCC voltage the turned-on threshold  $V_{\text{VCCon}}$  of at time  $t_1$ , the power cell is switched off, and the IC begins to operate with a soft-start. Due to power consumption of the IC and the fact that still no energy from the auxiliary winding to charge the VCC capacitor before the output voltage is built up, the VCC voltage

Version 2.1

drops (Phase II). Once the output voltage is high enough, the VCC capacitor receives then energy from the auxiliary winding from the time point  $t_2$  on. The VCC then will reach a constant value depending on output load.

Since there is a VCC undervoltage protection, the capacitance of the VCC capacitor should be selected to be high enough to ensure that enough energy is stored in the VCC capacitor so that the VCC voltage will never touch the VCC under voltage protection threshold  $V_{\text{VCCUVP}}$  before the output voltage is built up. Therefore, the capacitance should fulfill the following requirement:

$$C_{vcc} \ge \frac{I_{VCCop} \cdot (t_2 - t_1)}{V_{VCCon} - V_{VCCUVP}}$$
[2]

with  $I_{VCCop}$  the operating current of the controller.

## 3.2 Soft-start

At the time  $t_1$ , the IC begins to operate with a soft-start. By this soft-start the switching stresses for the switch, diode and transformer are minimised. The soft-start implemented in the ICE2QS01 is a digital time-based function. The preset soft-start time is **24ms** with 8 steps. The internal reference for the regulation voltage begins at 1.35V and with an increment of 0.35V for each following step.

### 3.3 Normal Operation

The PWM section of the IC can be divided into two main portions: PWM controller for normal operation and PWM controller for burst mode operation. The PWM controller for normal operation will be described in the following paragraphs, while the PWM controller for burst mode operation will be discussed in the next section.

The PWM controller for normal operation consists of digital signal processing circuit including an up/down counter, a zero-crossing counter (ZC-counter) and a comparator, and analog circuit including a current measurement unit and a comparator. The switch-on and -off time point is determined by the digital circuit and the analog circuit, respectively. As input information for the switch-on determination, the zero-crossing input signal and the value of the up/down counter are needed, while the feedback signal  $v_{\rm REG}$  and the current sensing signal  $v_{\rm CS}$  are necessary for the switch-off determination. Details about the operation of the PWM controller in normal operation are illustrated in the following paragraphs.

#### 3.3.1 Switch-on Determination

As mentioned above, the digital signal processing circuit consists of an up/down counter, a zero-crossing counter and a comparator. A ringing suppression time



controller is implemented to avoid mistriggering by the ring after MOSFET is turned off. Functionality of these parts is described as in the following.

#### 3.3.1.1 Up/down Counter

The up/down counter stores the number of zero crossing to be ignored before the main power switch is switched on after demagnetisation of the transformer. This value is a function of the regulation voltage, which contains information about the output power. Generally, a high output power results in a high regulation voltage. According to this information, the value in the up/down counter is changed to a low value in case of high regulation voltage, and to a high value in case of low regulation voltage. In ICE2QS01, the lowest value of the counter is 1 and the highest 7. Following text explains how the up/down counter value changes in responding to the regulation voltage  $v_{\text{REG}}$ . The regulation voltage  $v_{\text{REG}}$  is internally compared with three thresholds  $V_{\text{RL}}$ ,  $V_{\text{RH}}$  and  $V_{\text{RM}}$ . According to the results, the value in the up/down counter is changed, which is summarised in Table 1 and Figure 4 respectively.

Table 1 Operation of the up/down cou
--------------------------------------

V <sub>REG</sub>	up/down counter action
Always lower than V <sub>RL</sub>	Count upwards till 7
Once higher than V <sub>RL</sub> , but always lower than V <sub>RH</sub>	Stop counting, no value changing
Once higher than V <sub>RH</sub> , but always lower than V <sub>RM</sub>	Count downwards till 1
Once higher than $V_{RM}$	Set up/down counter to 1

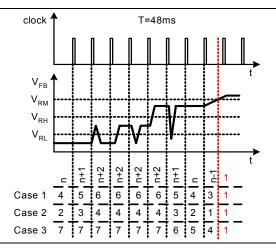


Figure 4 Up/down counter operation

According to the comparison results the up/down counter counts upwards, keeps unchanged or counts downwards. However, the value in up/down counter is

#### **Functional Description**

limited between 1 and 7. If the counter tends to count beyond this range, the attempt is ignored.

In normal case, the up/down counter can only be changed by one each time at the clock period of 48ms. However, to ensure a fast response to sudden load increase, the counter is set to 1 in the following switching period after the regulation voltage  $v_{\rm REG}$  exceeds the threshold  $V_{\rm RM}$ .

#### 3.3.1.2 Zero-Crossing Counter and Ringing Suppression Time Controller

In the system, the voltage from the auxiliary winding is applied to the zero-crossing pin through a RC network, which provides a time delay to the voltage from the auxiliary winding. Internally, this pin is connected to a clamping network, a zero-crossing detector, an output overvoltage (OP OVP) detector and a ringing suppression time controller.

During on-state of the power switch a negative voltage applies to the ZC pin. Through the internal clamping network, the voltage at the pin is clamped to certain level. However, it is highly recommended that a fast-recovery diode  $D_{zc}$  is added to block the negative voltage when the power switch is on. This is because the device in MOS technology is sensitive to negative voltage.

The voltage at the ZC pin  $v_{ZC}$  is compared with the threshold  $V_{ZCT1}$ . Once the voltage  $v_{ZC}$  crosses the threshold at its falling edge, a pulse is generated which is fed to the zero-crossing counter and the counter value increases by 1.

After MOSFET is turned on, there will be some oscillation on  $V_{DS}$ , which will also appear on the voltage on ZC pin. To avoid the MOSFET is turned on mistriggerred by such oscillation, a ringing suppression timer is implemented. The time is dependent on the voltage  $v_{ZC}$ . When the voltage  $v_{ZC}$  is lower than the threshold  $V_{ZCT2}$ , a longer preset time applies, while a shorter time is set when the voltage  $v_{ZC}$  is higher than the threshold.

The voltage  $v_{\rm ZC}$  is used for the output overvoltage protection, as well. Once the voltage at this pin is higher than the threshold  $V_{\rm OPOVP}$  during off-time of the main switch, the IC is latched off after a fixed blanking time.

To achieve the switch-on at voltage valley, the voltage from the auxiliary winding is fed to a time delay network (the RC network consists of  $D_{zc}$ ,  $R_{zc1}$ ,  $R_{zc2}$  and  $C_{zc}$  as shown in typical application circuit) before it is applied to the zero-crossing detector through the ZC pin. The needed time delay to the main oscillation signal  $\Delta t$  should be approximately one fourth of the oscillation period (by transformer primary inductor and drain-source capacitor) minus the propagation delay from the



detected zero-crossing to the switch-on of the main switch  $t_{delay}$ , theoretically:

$$\Delta t = \frac{T_{osc}}{4} - t_{delay}$$
 [3]

This time delay should be matched by adjusting the time constant of the RC network which is calculated as:

$$\tau_{td} = C_{zc} \cdot \frac{R_{zc1} \cdot R_{zc2}}{R_{zc1} + R_{zc2}}$$
[4]

#### 3.3.1.3 Switch-on Determination

In the system, turn-on of the power switch depends on the value of the up/down counter, the value of the zerocrossing counter and the voltage at the ZC pin  $v_{ZC}$ . Turn-on happens only when the value in the both counters are the same and the voltage at the ZC is lower than the threshold  $V_{ZCT1}$ . For comparison of the values from both counters, a digital comparator is used. Once these counters have the same value, the comparator generates a signal which sets the on/off flip-flop, only when the voltage  $v_{ZC}$  is lower than the threshold  $V_{ZCT1}$ .

Another signal which may trigger the digital comparator is the output of a  $T_{sMax}$  clock signal, which limits the maximum off time to avoid the low-frequency operation.

During active burst mode operation, the digital comparator is disabled and no pulse will be generated.

### **Functional Description**

#### 3.3.2 Switch-off Determination

In the converter system, the primary current is sensed by an external shunt resistor, which is connected between low-side terminal of the main power switch and the common ground. The sensed voltage across the shunt resistor  $v_{CS}$  is applied to an internal current measurement unit, and its output voltage  $v_1$  is compared with the regulation voltage  $v_{reg}$ . Once the voltage  $v_1$  exceeds the voltage  $v_{REG}$ , the output flip-flop is reset. As a result, the main power switch is switched off. The relationship between the  $v_1$  and the  $v_{cs}$  is described by:

$$v_1 = 3.3 \cdot v_{CS} + 0.7$$
[5]

To avoid mistriggering caused by the voltage spike across the shunt resistor after switch-on of the main power switch, a 330ns leading edge blanking time applies to output of the comparator.

#### 3.3.3 Foldback Point Correction

In addition to the cycle-by-cylce primary current limitation, the IC incorporats a foldback point correction. The current limit on CS pin voltage is now a time dependent one. If the mains input voltage is high, the MOSFET on time will be short and the current limit will be low. In such a way, the maximum output power for the SMPS designed with ICE2QS01 will be nearly constant against the variations of mains input voltage. The current sense voltage limit versus the MOSFET maximum on time is shown in Figure 5.

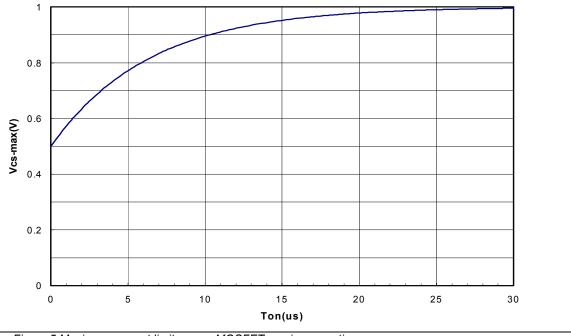


Figure 5 Maximum current limit versus MOSFET maximum on time

Version 2.1



#### **Functional Description**

# 3.4 Active Burst Mode Operation

At very low load condition, the IC enters active burst mode operation to minimize the input power. Details about active burst mode operation are explained in the following paragraphs.

#### 3.4.1 Entering Active Burst Mode Operation

For determination of entering active burst mode operation, three conditions apply:

the regulation voltage is lower than the threshold of  $V_{EB}(1.1V)$ . Accordingly, the peak voltage across the shunt resistor is 0.11V;

the up/down counter has its maximal value of 7; and

a certain blanking time (24ms).

Once all of these conditions are fulfilled, the active burst mode flip-flop is set and the controller enters burst mode operation. This multi-conditional determination for entering active burst mode operation prevents mistriggering of entering active burst mode operation, so that the controller enters active burst mode operation only when the output power is really low during the preset blanking time.

#### 3.4.2 During Active Burst Mode Operation

After entering the Active Burst Mode the regulation voltage rises as  $V_{OUT}$  starts to decrease due to the inactive PWM section. One comparator observes the regulation signal if the voltage level  $V_{BH}$  (3.6V) is exceeded. In that case the internal circuit is again activated by the internal bias to start with swtiching.

Turn-on of the power MOSFET is triggered by the timer. The PWM generator for burst mode operation composes of a timer with a fixed frequency of 80kHz, typically, and an analog comparator. Turn-off is resulted by comparison of the voltage signal v<sub>1</sub> with an internal threshold, by which the voltage across the shunt resistor V<sub>csB</sub> is 0.25V, accordingly. A turn-off can also be triggered by the maximal duty ratio controller which sets the maximal duty ratio to 50%. In operation, the output flip-flop will be reset by one of these signals which come first.

If the output load is still low, the regulation signal decreases as the PWM section is operating. When regulation signal reaches the low threshold  $V_{BL}(3.0V)$ , the internal bias is reset again and the PWM section is disabled until next time regultaion signal increases beyond the  $V_{BH}$  threshold. If working in active burst mode the regulation signal is changing like a saw tooth between 3.0V and 3.6V shown in Figure 6.

#### 3.4.3 Leaving Active Burst Mode

The regulation voltage immediately increases if there is a high load jump. This is observed by one comparator. As the current limit is 25% during active burst mode a certain load is needed so that regulation voltage can exceed V<sub>LB</sub> (4.5V). After leaving active busrt mode, maximum current can now be provided to stabilize V<sub>O</sub>. In addition, the up/down counter will be set to 1 immediately after leaving active burst mode. This is helpful to decrease the output voltage undershoot.

#### 3.4.4 IC Power Supply During Active Burst Mode

During active burst mode operation, the power cell is activated again. Once the power from the auxiliary winding is not high enough to keep the VCC voltage above the preset value of  $V_{VCCBL}$ , the power cell keeps the VCC voltage at the preset value  $V_{VCCBL}$ . Otherwise, if the VCC voltage is still above this value, no current flows through the power cell though it is activated.

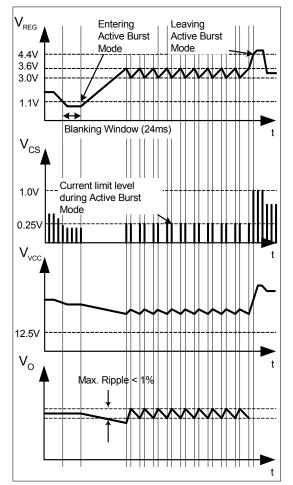


Figure 6 Signals in active burst mode

Version 2.1



## **Functional Description**

# 3.5 Protection Functions

The IC provides full protection functions. The following table summarizes these protection functions.

 Table 2
 Protection features

VCC Overvoltage	Auto Restart Mode
VCC Undervoltage	Auto Restart Mode
Overload/Open Loop	Auto Restart Mode
Output Overvoltage	Latched Off Mode
Short Winding	Latched Off Mode

During operation, the VCC voltage is continuously monitored. In case of an under- or an over-voltage, the IC is reset and the main power switch is then kept off. After the VCC voltage falls below the threshold  $V_{VCCUVP}$ , the power cell is activated. The VCC capacitor is then charged up. Once the voltage exceeds the threshold  $V_{VCCon}$ , the IC begins to operate with a new soft-start.

In case of open control loop or output over load, the regulation voltage will be pulled up . After a blanking time of 24ms, the IC enters auto-restart mode. The blanking time here enables the converter to provide a high power in case the increase in  $V_{REG}$  is due to a sudden load increase. During off-time of the power switch, the voltage at the zero-crossing pin is monitored for output over-voltage detection. If the voltage is higher than the preset threshold v<sub>OPOVP</sub>, the IC is latched off after the preset blanking time.

If the voltage at the current sensing pin is higher than the preset threshold  $v_{\rm csSW}$  during on-time of the power switch, the IC is latched off. This is short-winding protection.

During latch-off protection mode, the power cell is activated and it keeps the VCC voltage at the level of  $V_{\rm VCCBL.}$ 



# 4 Electrical Characteristics

# 4.1 Absolute Maximum Ratings

Note: Absolute maximum ratings are defined as ratings, which when being exceeded may lead to destruction of the integrated circuit. For the same reason make sure, that any capacitor that will be connected to pin 7 (VCC) is discharged before assembling the application circuit.

Parameter	Symbol	Limi	t Values	Unit	Remarks
		min.	max.		
HV Voltage	V <sub>HV</sub>	-	500	V	
VCC Supply Voltage	V <sub>VCC</sub>	-0.3	27	V	
REG Voltage	V <sub>REG</sub>	-0.3	5.0	V	
ZC Voltage	V <sub>ZC</sub>	-0.3	5.0	V	
CS Voltage	V <sub>CS</sub>	-0.3	5.0	V	
OUT Voltage	V <sub>OUT</sub>	-0.3	27	V	
Junction Temperature	Tj	-40	125	°C	
Storage Temperature	Τ <sub>s</sub>	-55	150	°C	
Thermal Resistance Junction-Ambient	R <sub>thJA</sub>	-	90	K/W	PG-DIP-8
ESD Capability	V <sub>ESD</sub>	-	2	kV	Human body model <sup>1)</sup>

<sup>1)</sup> According to EIA/JESD22-A114-B (discharging a 100pF capacitor through a  $1.5k\Omega$  series resistor)

# 4.2 Operating Range

Note: Within the operating range the IC operates as described in the functional description.

Parameter	Symbol	Limit Values		Limit Values		Limit Values		Limit Values		Unit	Remarks
		min.	max.								
VCC Supply Voltage	V <sub>VCC</sub>	V <sub>VCCUVP</sub>	$V_{VCCOVP}$	V							
Junction Temperature	T <sub>jCon</sub>	-25	125	°C							

Note: All voltages are measured with respect to ground (Pin 8). The voltage levels are valid if other ratings are not violated.



# 4.3 Characteristics

#### 4.3.1 Supply Section

Note: The electrical characteristics involve the spread of values guaranteed within the specified supply voltage and junction temperature range  $T_j$  from – 25 °C to 125°C. Typical values represent the median values, which are related to 25°C. If not otherwise stated, a supply voltage of  $V_{CC}$  = 18 V is assumed.

Parameter	Symbol	Limit Values			Unit	Test Condition
		min.	typ.	max.		
Start-Up Current	I <sub>VCCstart</sub>	-	300	550	μA	V <sub>VCC</sub> = 21V
VCC Charge Current	I <sub>VCCcharge1</sub>			5.0	mA	$V_{VCC} = 0V$
	I <sub>VCCcharge2</sub>	0.55	1.05	1.60	mA	V <sub>VCC</sub> = 1V
	I <sub>VCCcharge3</sub>	-	0.88	-	mA	V <sub>VCC</sub> = 21V
Leakage Current of Power Cell	I <sub>StartLeak</sub>	-	0.2	50	μΑ	V <sub>HV</sub> = 610V at T <sub>j</sub> = 100°C
Supply Current in normal operation	I <sub>VCCop</sub>	-	2.5	3.6	mA	Output low
Supply Current in Auto Restart Mode with Inactive Gate	I <sub>VCCrestart</sub>	-	300	-	μA	
Supply Current in Latch-off Mode	I <sub>VCClatch</sub>	-	300	-	μΑ	
Supply Current in Burst Mode with Inactive Gate	I <sub>VCCburst</sub>	-	500	950	μΑ	V <sub>REG</sub> = 2.5V
Supply Voltage with no power from auxiliary winding in burst mode or in latch-off mode	V <sub>VCCBL</sub>	-	12.5	-	V	V <sub>HV</sub> = 100V
VCC Turn-On Threshold	V <sub>VCCon</sub>	21.2	22.0	22.8	V	
Internal Reference Voltage	$V_{REF}$	4.8	5.0	5.2	V	measured at pin REG I <sub>REG</sub> = 0



#### 4.3.2 PWM Section

Parameter	Symbol		Limit Val	ues	Unit	Test Condition
		min.	typ.	max.		
Regulation Pull-Up Resistor	R <sub>REG</sub>	14	23	33	kΩ	
PWM-OP Gain	A <sub>V</sub>	3.18	3.3	-	-	
Offset for Voltage Ramp	V <sub>os</sub>	0.63	0.7	-	V	
Soft-Start time	t <sub>SOFTS</sub>	18	21	38	ms	
Zero crossing threshold voltage	V <sub>ZCT1</sub>	20	50	110	mV	
Ringing suppression threshold	V <sub>ZCT2</sub>		0.7		V	
Minimum ringing suppression time	t <sub>ZCRST1</sub>	2.2	4.2	5.5	μs	$V_{ZC} > V_{ZCT2}$
Maximum ringing suppression time	t <sub>ZCRST2</sub>	-	42	-	μs	V <sub>ZC</sub> < V <sub>ZCT2</sub>
Threshold to set Up/Down Counter to one	V <sub>RM</sub>		3.9		V	
Threshold for downward counting	V <sub>RH</sub>		3.2		V	
Threshold for upward counting	V <sub>RL</sub>		2.5		V	
Counter time <sup>1)</sup>	t <sub>COUNT</sub>		48		ms	
Maximum restart time in normal operation	t <sub>sMax</sub>	33	42	60	μS	V <sub>ZC</sub> <v<sub>ZCT1</v<sub>
Leading Edge Blanking	t <sub>LEB</sub>	200	330	460	ns	
Peak current limitation in normal operation	V <sub>csth</sub>	0.95	1.0	1.05	V	
Regulation voltage for entering Burst Mode	V <sub>EB</sub>		1.1		V	
Regulation voltage for leaving Burst Mode	V <sub>LB</sub>		4.5		V	
Regulation voltage for burst-on	V <sub>BH</sub>		3.6		V	
Regulation voltage for burst-off	V <sub>BL</sub>		3.0		V	
Fixed Switching Frequency in Burst Mode	$f_{sB}$	64	80	96	kHz	
Max. Duty Cycle in Burst Mode	D <sub>maxB</sub>		0.5			
Peak Current Limitation in Burst Mode	V <sub>csB</sub>	0.22	0.25	0.3	V	
1) The parameter is not subject t	o production	n test - ver	ified by de	sign/chara	cterizatio	n



#### 4.3.3 Protection

Parameter	Symbol		Limit Val	ues	Unit	Test Condition
		min.	typ.	max.		
VCC overvoltage threshold	V <sub>VCCOVP</sub>	24	25.0	26	V	
VCC undervoltage threshold	V <sub>VCCUVP</sub>	10.3	11.0	11.7	V	
Over Load or Open Loop Detection threshold for OLP protection at REG pin	V <sub>OLP</sub>		4.5		V	
Over Load or Open Loop Protection Blanking Time	T <sub>OLP-B</sub>	16	24	35	ms	
Output Overvoltage detection threshold at the ZC pin	V <sub>OPOVP</sub>		4.5		V	
Threshold for short winding protection	$V_{csSW}$		1.68		V	

Note: The trend of all the voltage levels in the Control Unit is the same regarding the deviation except  $V_{VCCOVP}$ 

#### 4.3.4 Gate Driver

Parameter	Symbol		Limit Valu	Jes	Unit	Test Condition
		min.	typ.	max.		
Output voltage at logic low	V <sub>GATElow</sub>		0.7		V	I <sub>OUT</sub> = 20mA
Output voltage at logic high	V <sub>GATEhigh</sub>		10.0		V	I <sub>OUT</sub> = -20mA
Output voltage active shut down	V <sub>GATEasd</sub>		1.0		V V	V <sub>VCC</sub> = 7V I <sub>OUT</sub> = 20mA
Rise Time	t <sub>rise</sub>	-	100	-	ns	C <sub>OUT</sub> = 4.7nF
Fall Time	t <sub>fall</sub>	-	25	-	ns	C <sub>OUT</sub> = 4.7nF



ICE2QS01

# **Outline Dimension**

# 5 Outline Dimension

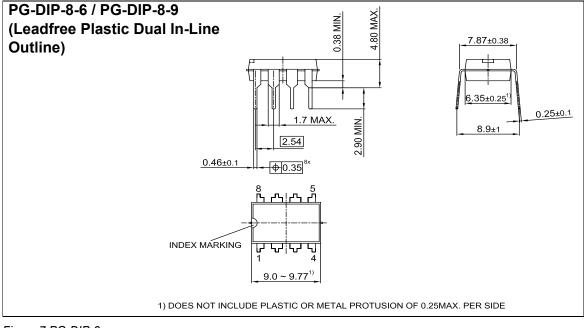


Figure 7 PG-DIP-8 \*Dimensions in mm

# **Total Quality Management**

Qualität hat für uns eine umfassende Bedeutung. Wir wollen allen Ihren Ansprüchen in der bestmöglichen Weise gerecht werden. Es geht uns also nicht nur um die Produktqualität – unsere Anstrengungen gelten gleichermaßen der Lieferqualität und Logistik, dem Service und Support sowie allen sonstigen Beratungs- und Betreuungsleistungen.

Dazu gehört eine bestimmte Geisteshaltung unserer Mitarbeiter. Total Quality im Denken und Handeln gegenüber Kollegen, Lieferanten und Ihnen, unserem Kunden. Unsere Leitlinie ist jede Aufgabe mit "Null Fehlern" zu lösen – in offener Sichtweise auch über den eigenen Arbeitsplatz hinaus – und uns ständig zu verbessern.

Unternehmensweit orientieren wir uns dabei auch an "top" (Time Optimized Processes), um Ihnen durch größere Schnelligkeit den entscheidenden Wettbewerbsvorsprung zu verschaffen.

Geben Sie uns die Chance, hohe Leistung durch umfassende Qualität zu beweisen. Quality takes on an allencompassing significance at Semiconductor Group. For us it means living up to each and every one of your demands in the best possible way. So we are not only concerned with product quality. We direct our efforts equally at quality of supply and logistics, service and support, as well as all the other ways in which we advise and attend to you.

Part of this is the very special attitude of our staff. Total Quality in thought and deed, towards co-workers, suppliers and you, our customer. Our guideline is "do everything with zero defects", in an open manner that is demonstrated beyond your immediate workplace, and to constantly improve.

Throughout the corporation we also think in terms of Time Optimized Processes (top), greater speed on our part to give you that decisive competitive edge.

Give us the chance to prove the best of performance through the best of quality – you will be convinced.

Wir werden Sie überzeugen.

http://www.infineon.com

Published by Infineon Technologies AG