



# Datasheet - MAP3511

## Average Current Control Buck Controller for LED Backlight

### General Description

MAP3511 is an average-mode current control buck controller for LED backlight application. It does not require an additional dimming MOSFET and utilizes constant off-time control and average current control feedback without external loop compensation or high-side current sensing.

MAP3511 features  $\pm 1\%$  CS voltage accuracy and has dedicated analog dimming input up to 3V. It can be powered from 8.5V ~ 18V supply.

MAP3511 provides MOSFET DS short detection (FLT output), SCP and UVLO.

MAP3511 is available 8 leads SOIC with Halogen-free (fully RoHS compliant).

### Features

- 8.5V to 18V Input Voltage Range
- Average-Mode Current Control
- Programmable Constant off-time
- Up to 3V Analog Dimming Input
- $\pm 1\%$  CS Voltage Accuracy
- Direct PWM Dimming Input
- Fault Output (MOSFET Drain-Source Short)
- Short Circuit Protection
- UVLO
- 8 Leads SOIC Package with Halogen-free

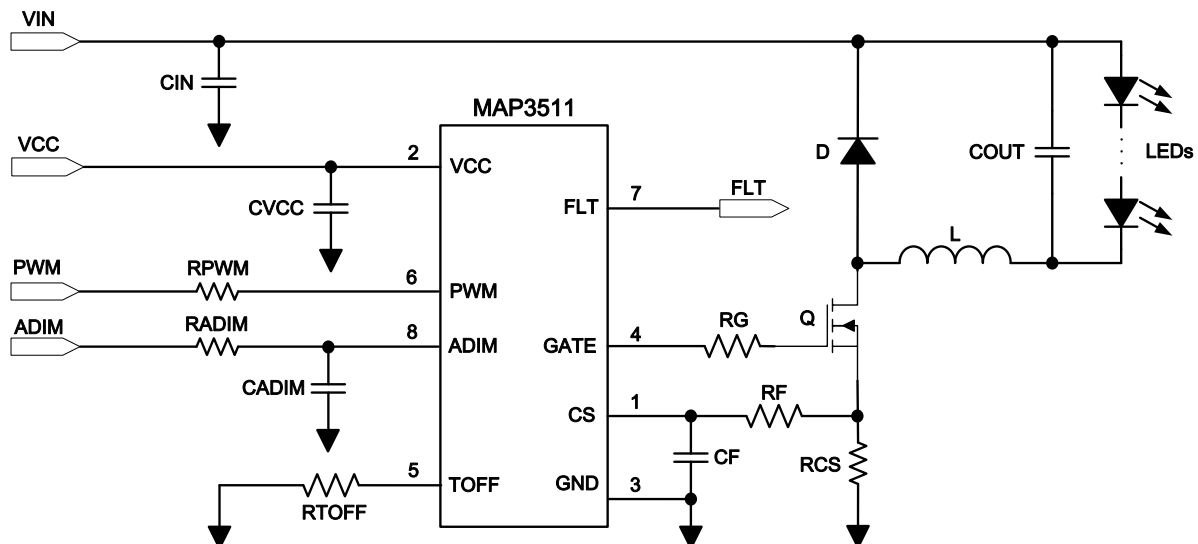
### Applications

- High Brightness white LED backlighting for LCD TVs
- General LED lighting applications

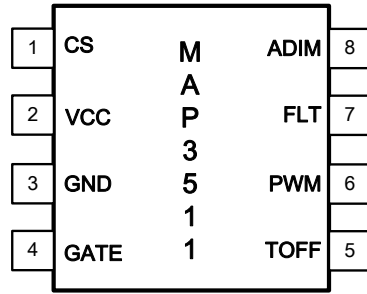
### Ordering Information

Part Number	Top Marking	Ambient Temperature Range	Package	RoHS Status
MAP3511SIRH	MAP3511	-40°C to +85°C	8Leads SOIC	Halogen Free

### Typical Application



**Pin Configuration**



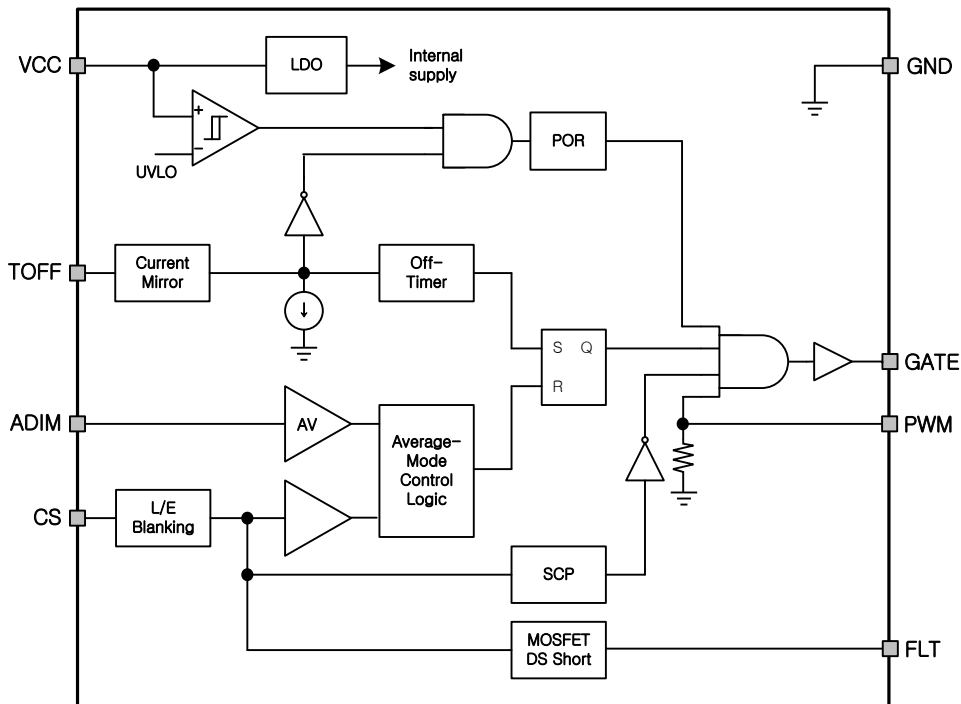
SOIC-8L

**Pin Description**

8leads SOIC	Name	Description
1	CS	External current sense (Note 1)
2	VCC	Power supply input. Need external bypass capacitor
3	GND	Ground
4	GATE	GATE driver output to drive external NMOSFET
5	TOFF	Setting for GATE off-time(Note 2)
6	PWM	PWM signal input for dimming
7	FLT	Fault Output
8	ADIM	Setting for LED current thru external DC voltage

**Note 1:** Connect external resistor to GND to sense the external power MOSFET source current as shown in typical application  
**Note 2:** Connect external resistor to GND to set GATE off-time as shown in typical application

**Functional Block Diagram**



### Absolute Maximum Ratings<sup>(Note 1)</sup>

Symbol	Parameter	Min	Max	Unit
$V_{VCC}, V_{GATE}, V_{PWM}$	VCC, GATE, PWM pins Voltage	-0.3	20	V
$V_{CS}, V_{TOFF}, V_{ADIM}, V_{FLT}$	CS, TOFF, ADIM, FLT pins Voltage	-0.3	5	V
$T_{PAD}$	Soldering Lead/ Pad Temperature 10sec		300	°C
$T_J$	Junction Temperature	-40	+150	°C
$T_S$	Storage Temperature	-65	+150	°C
ESD	HBM on All Pins (Note 2)	-2000	+2000	V
	MM on All Pins (Note 3)	-200	+200	

**Note 1:** Stresses beyond the above listed maximum ratings may damage the device permanently. Operating above the recommended conditions for extended time may stress the device and affect device reliability. Also the device may not operate normally above the recommended operating conditions. These are stress ratings only.

**Note 2:** ESD tested per JESD22A-114.

**Note 3:** ESD tested per JESD22A-115.

### Recommended Operating Conditions<sup>(Note 1)</sup>

Parameter	Min	Max	Unit	
$V_{VCC}$	Supply Input Voltage	8.5	18.0	V
$V_{ADIM}$	ADIM Input Range	0.5	3.0	V
$T_A$	Ambient Temperature (Note 2)	-40	+85	°C

**Note 1:** Normal operation of the device is not guaranteed if operating the device over outside range of recommended conditions.

**Note 2:** The ambient temperature may have to be derated if used in high power dissipation and poor thermal resistance conditions.

### Package Thermal Resistance<sup>(Note 1)</sup>

Parameter	$\theta_{JA}$	Unit
MAP3511SIRH 8 Leads SOIC	94.6	°C/W

**Note 1:** Multi-layer PCB based on JEDEC standard (JESD51-7)

## Electrical Characteristics

Unless noted,  $V_{VCC} = 12V$ ,  $C_{VCC} = 1.0\mu F$ , and typical values are tested at  $T_A = 25^\circ C$ .

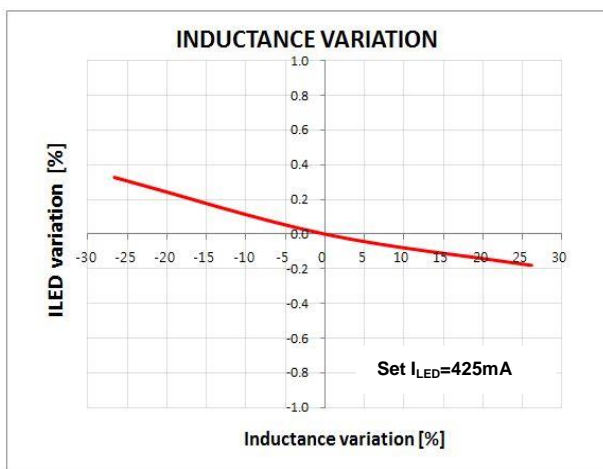
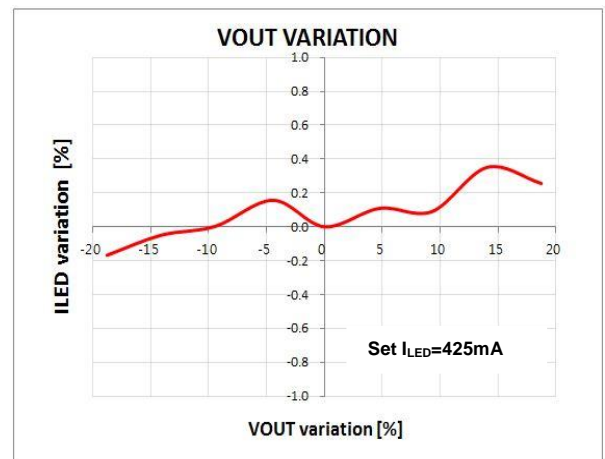
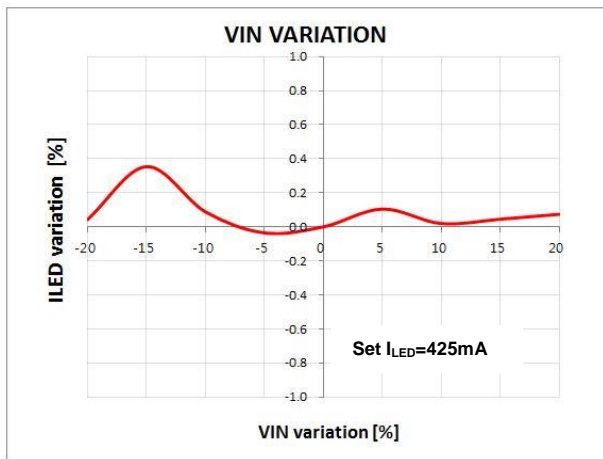
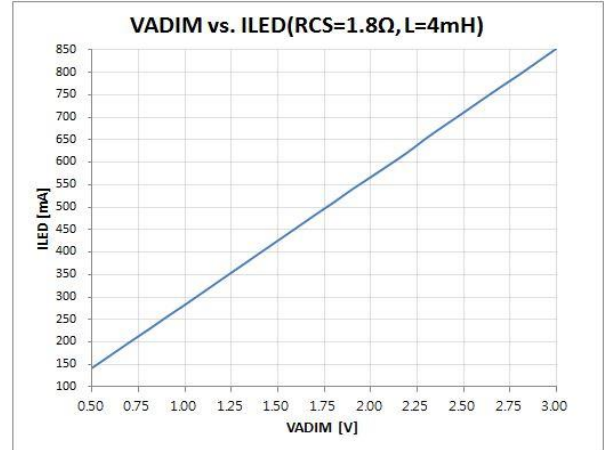
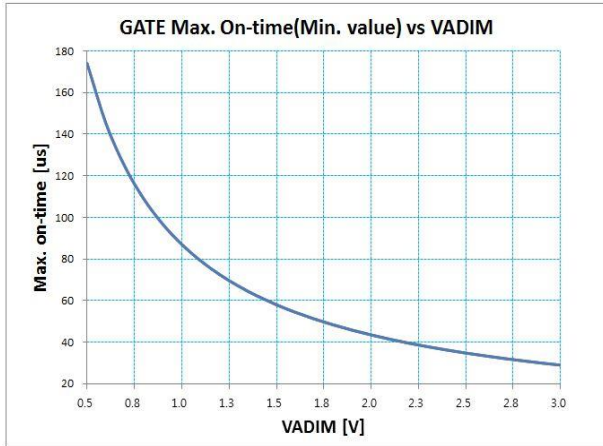
Parameter		Test Condition	Min	Typ	Max	Unit
<b>Supply</b>						
$V_{VCC}$	Input Voltage Range		8.5		18	V
$I_Q$	Quiescent Current	$V_{PWM} = 5V$ , $V_{CS} = 0V$		1.6		mA
$V_{UVLO}$	Under Voltage Lockout Threshold Voltage on VCC pin	Release threshold(rising $V_{VCC}$ )	7.5	8.0	8.5	V
		Lockout hysteresis(falling $V_{VCC}$ )	0.5	1.0	1.5	
<b>OFF Timer</b>						
$t_{OFF}$	GATE Off-time	$R_{TOFF} = 52k\Omega$	4.5	5.0	5.5	us
		$R_{TOFF} = 104k\Omega$	9	10	11	
$t_{ON\_MIN}$	Min. On-Time			300		ns
$t_{ON\_MAX}$	Max. On-Time	$V_{ADIM} = 3V$		33		us
$t_{OFF\_MIN}$	Min. Off-Time			1.0	1.1	us
$D_{MAX}$	Max. Duty Cycle	$V_{ADIM} = 3V$ , $t_{OFF} = 1\mu s$		97		%
<b>GATE Driver</b>						
$I_{SOURCE}$	GATE Source Current	$V_{GATE} = 0V$	400			mA
$I_{SINK}$	GATE Sink Current	$V_{GATE} = V_{VCC} = 12V$	800			mA
$t_{RISE}$	GATE Output Rising Time	$C_{GATE} = 1nF$ , $V_{VCC} = 12V$		50	85	ns
$t_{FALL}$	GATE Output Falling Time	$C_{GATE} = 1nF$ , $V_{VCC} = 12V$		25	45	ns
<b>Current Sense &amp; Dimming</b>						
$V_{ADIM}$	ADIM Input Voltage Range		0.5		3.0	V
$A_V$	VADIM to CS Voltage Ratio			0.5075		V/V
$V_{CS}$	CS Voltage	$V_{ADIM} = 0.5V$	0.2512		0.2563	V
		$V_{ADIM} = 3.0V$	1.5073		1.5377	
$t_{LEB}$	Leading Edge Blanking Time			300		ns
<b>PWM Interface</b>						
$V_{PWM}$	Logic Input Level on PWM pin	$V_{PWM\_L}$ : Logic Low			0.8	V
		$V_{PWM\_H}$ : Logic High	2.0			
$R_{PWM}$	Pull-down Resistor on PWM pin	$V_{PWM} = 4V$	50	100	150	k $\Omega$
<b>Protection</b>						
$A_{VSCP}$	VADIM to SCP Voltage Ratio			1.45		V/V
$V_{SCP}$	SCP Detection Threshold Voltage on CS pins	$V_{ADIM} = 0.5V$	0.6888	0.7250	0.7613	V
		$V_{ADIM} = 1.0V$	1.3775	1.4500	1.5225	
		$V_{ADIM} = 2.5V$	3.4438	3.6250	3.8063	
$t_{DELAY}$	SCP Delay Time			300		ns
$t_{RESTART}$	Restart Time			1		ms
$V_{SCPDS}$	MOSFET DS Short Detection Threshold Voltage on CS pin	$V_{ADIM} = 0.5V$ (Note 1, 2)		0.25		V
		$V_{ADIM} = 2.5V$ (Note 1, 2)		1.25		
$V_{FLT}$	FLT pin High Voltage		4.5		5	V

**Note 1:** These parameters, although guaranteed by design, are not tested in mass production.

**Note 2:** At start-up( $V_{VCC} \geq V_{UVLO}$  release threshold) or  $V_{PWM} =$  Logic 'High' at running

### Typical Operating Characteristics

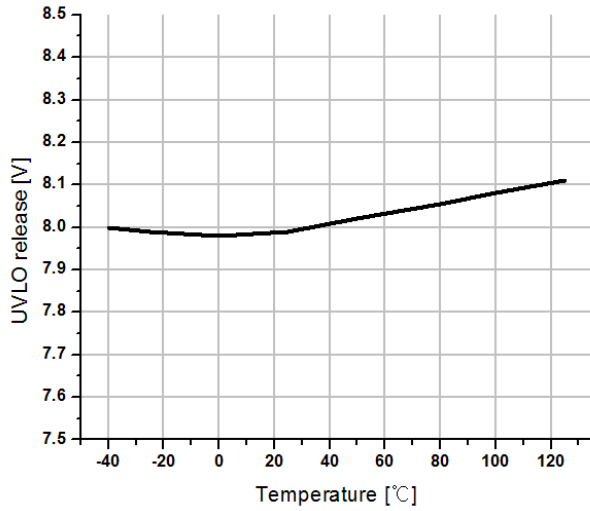
Unless otherwise noted,  $V_{CC} = 12V$  and  $T_A = 25^\circ C$ .



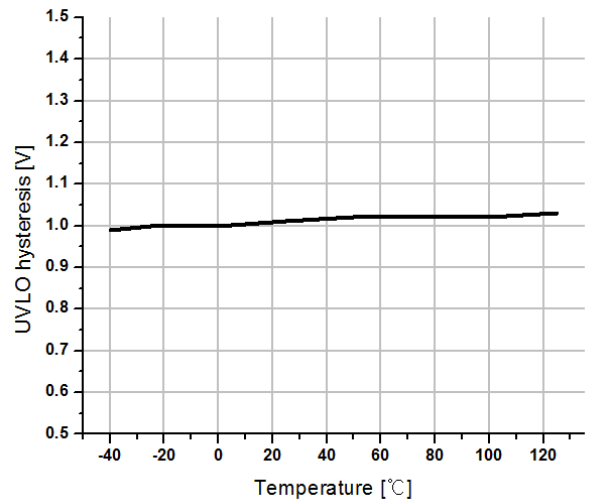
### Typical Operating Characteristics

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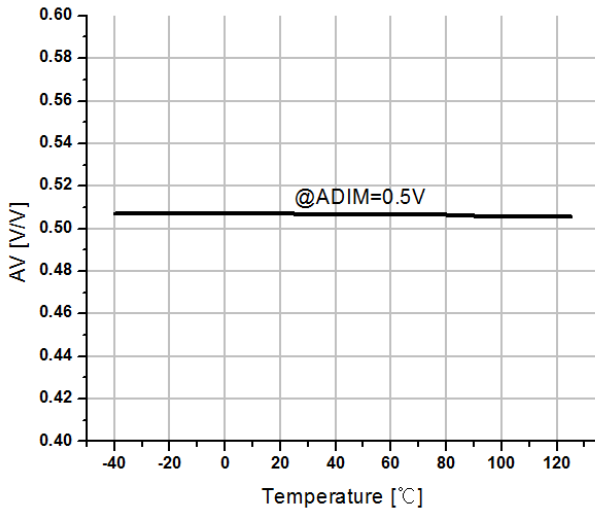
**$V_{UVLO(RELEASE)}$  vs. Temp**



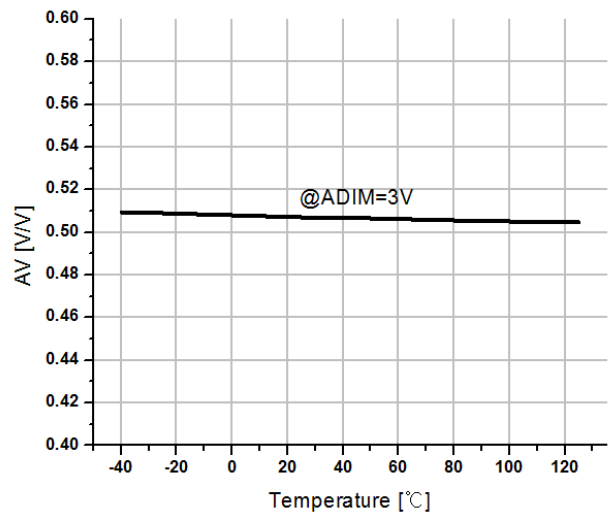
**$V_{UVLO(HYS)}$  vs. Temp.**



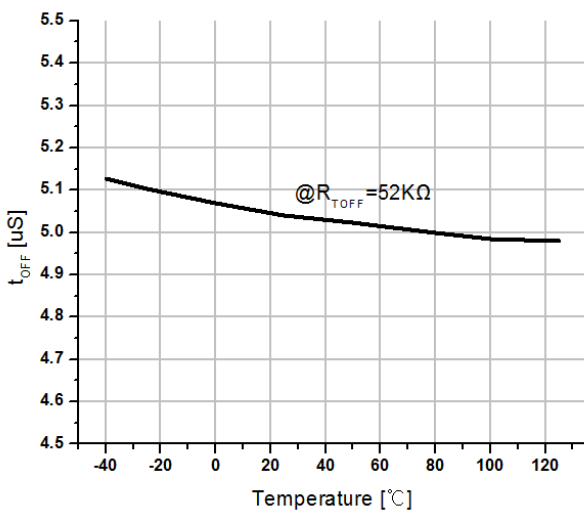
**$A_V(V_{ADIM=0.5V})$  vs. Temp**



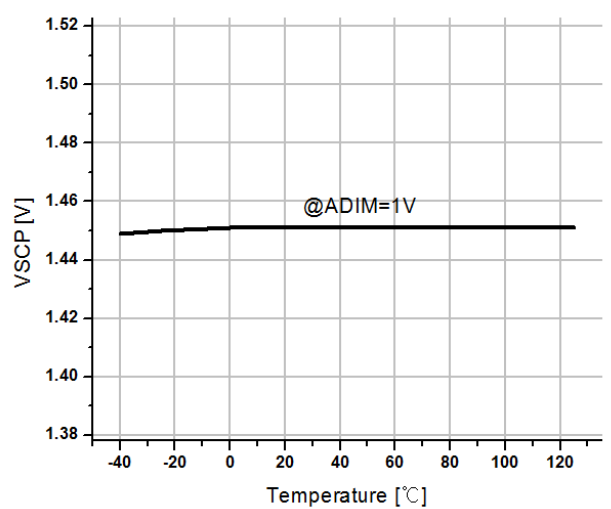
**$A_V(V_{ADIM=3.0V})$  vs. Temp**



**$t_{OFF}(R_{TOFF}=52k\Omega)$  vs. Temp**



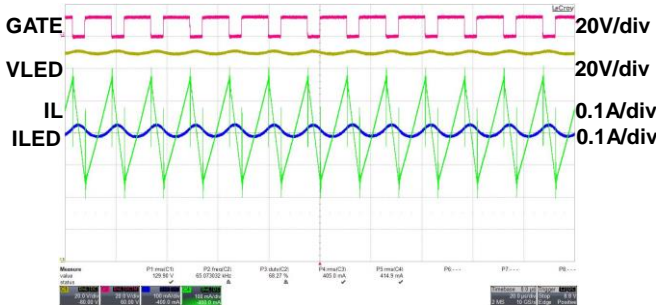
**$V_{SCP}(V_{ADIM=1V})$  vs. Temp**



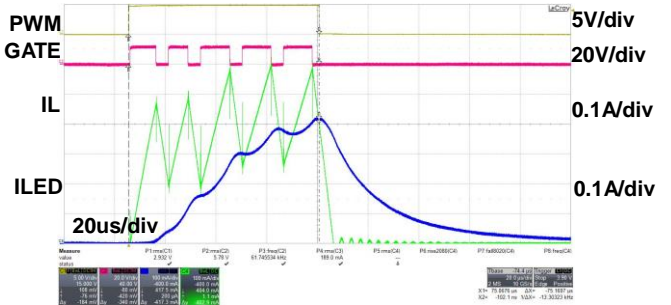
### Typical Operating Characteristics

Unless otherwise noted,  $V_{VCC} = 12V$  and  $T_A = 25^\circ C$ .

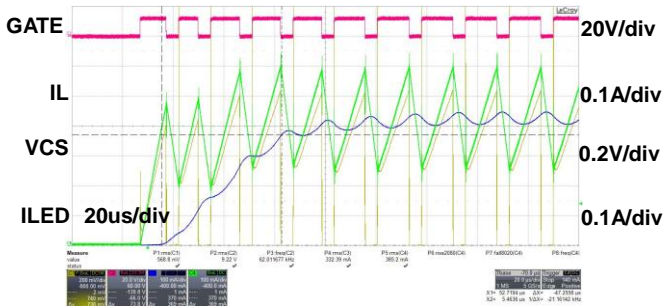
#### Constant Current Control



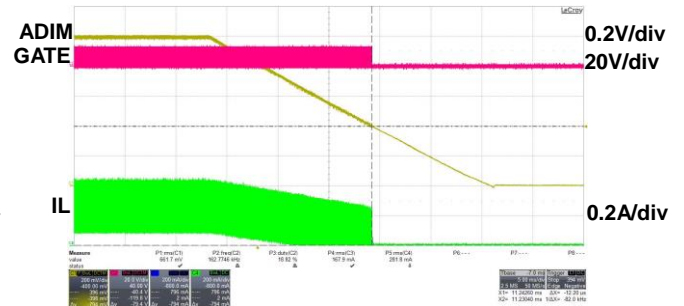
#### Min. Dimming( $C_{OUT}=330nF$ )



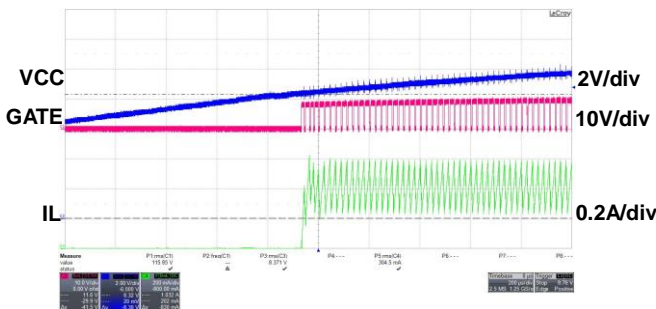
#### Soft-start( $C_{OUT}=330nF$ )



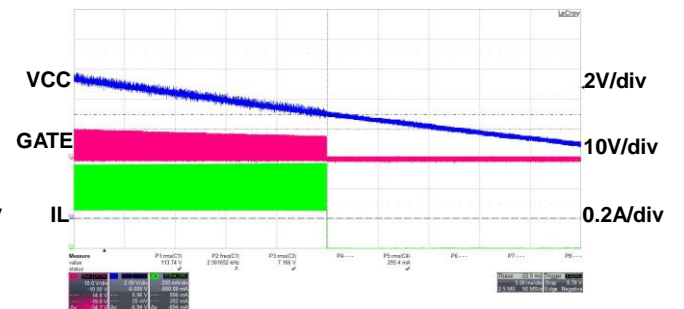
#### $V_{ADIM}$ Off



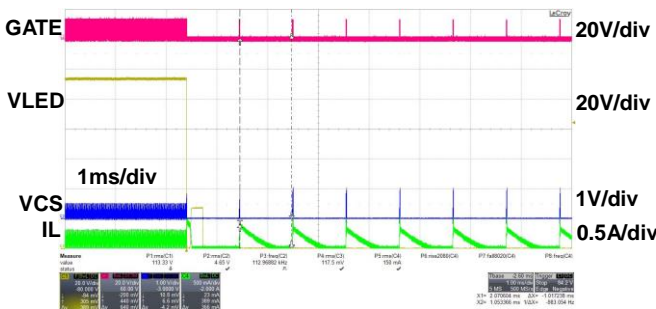
#### UVLO Release



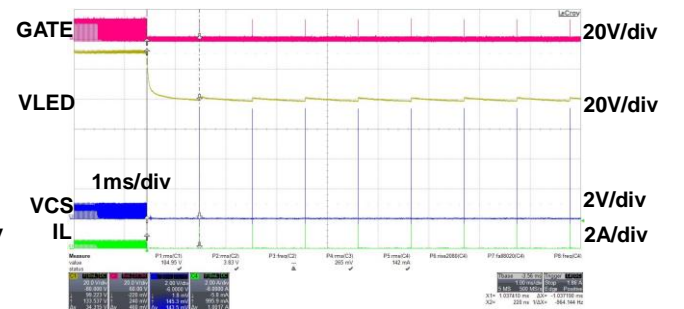
#### UVLO Lockout



#### SCP(LED All Short)



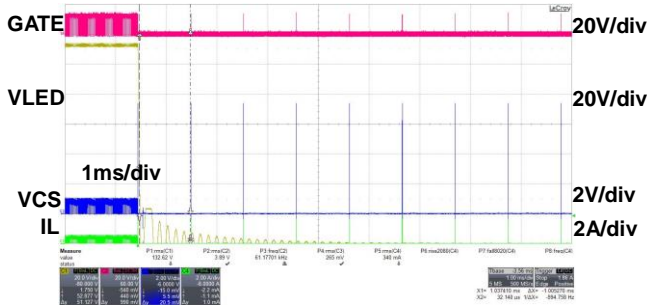
#### SCP(Inductor Short)



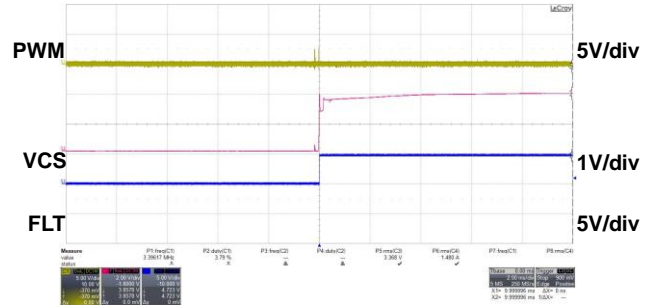
### Typical Operating Characteristics

Unless otherwise noted,  $V_{VCC} = 12V$  and  $T_A = 25^\circ C$ .

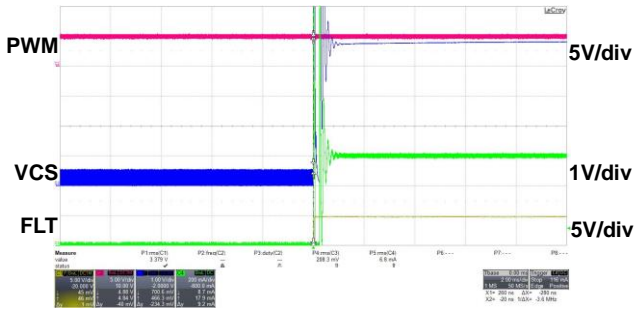
#### SCP(Catch Diode Short)



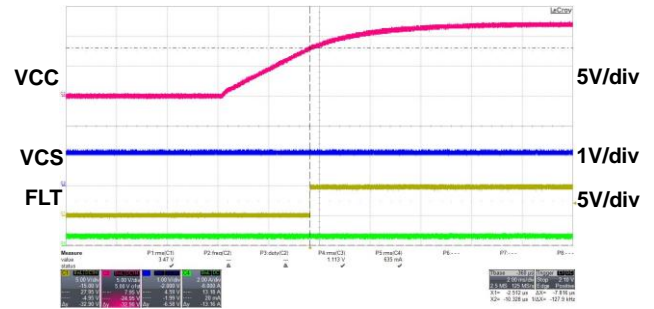
#### FLT Output(@ PWM Off @ Running)



#### FLT Output(@ PWM On @ Running)



#### FLT Output(@ PWM On or Off @ Start-up)





## Functional Description

### GENERAL DESCRIPTION

The MAP3511 is a low-side single switch control, constant off-time buck controller optimized to LED backlight applications. The IC employs unique average-mode current control architecture which provides precise LED current accuracy. It does not require any external loop compensation or high side current sensing.

The IC operates at continuous conduction mode to reduce output ripple, thus small output capacitor is available. The off time is user adjustable through the selection of an external resistor, this allows the design to be optimized for a given switching frequency range and supports wide range of input voltages.

### RCS SETTING

The current sense resistor value is calculated by following equation.

$$R_{CS} = \frac{0.5075 \times V_{ADIM}}{I_{LED}} [\Omega]$$

### ROFF SETTING

The off-time of the GATE driver is programmed by an external resistor connected between the TOFF pin and ground. Do not leave this pin open. The off-time is calculated by following equation.

$$R_{TOFF} = \frac{0.4 \times t_{OFF} [us] \times 1000}{38.4} [k\Omega]$$

### PWM DIMMING

The brightness control of the LEDs is performed by a pulse-width modulation. The GATE output is valid only at PWM on period. this means that the GATE maintains off-state as long as PWM signal is logic low.

Care should be taken to test at low PWM duty-cycle because the output capacitor can affect rising and falling time of LED current due to its charging and discharging time.

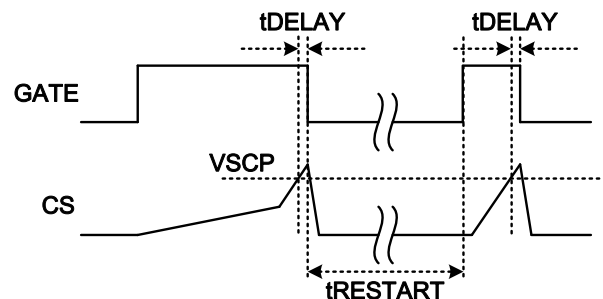
### UVLO

The MAP3511 has an Internal LDO regulator to supply internal circuit and GATE driver. This LDO is powered up when the VCC voltage rises to UVLO release threshold.

If the voltage on the VCC pin falls below UVLO lockout threshold, the device turns-off the GATE output and be reset. This ensures fail-safe operation for VCC input voltage falling.

### SCP

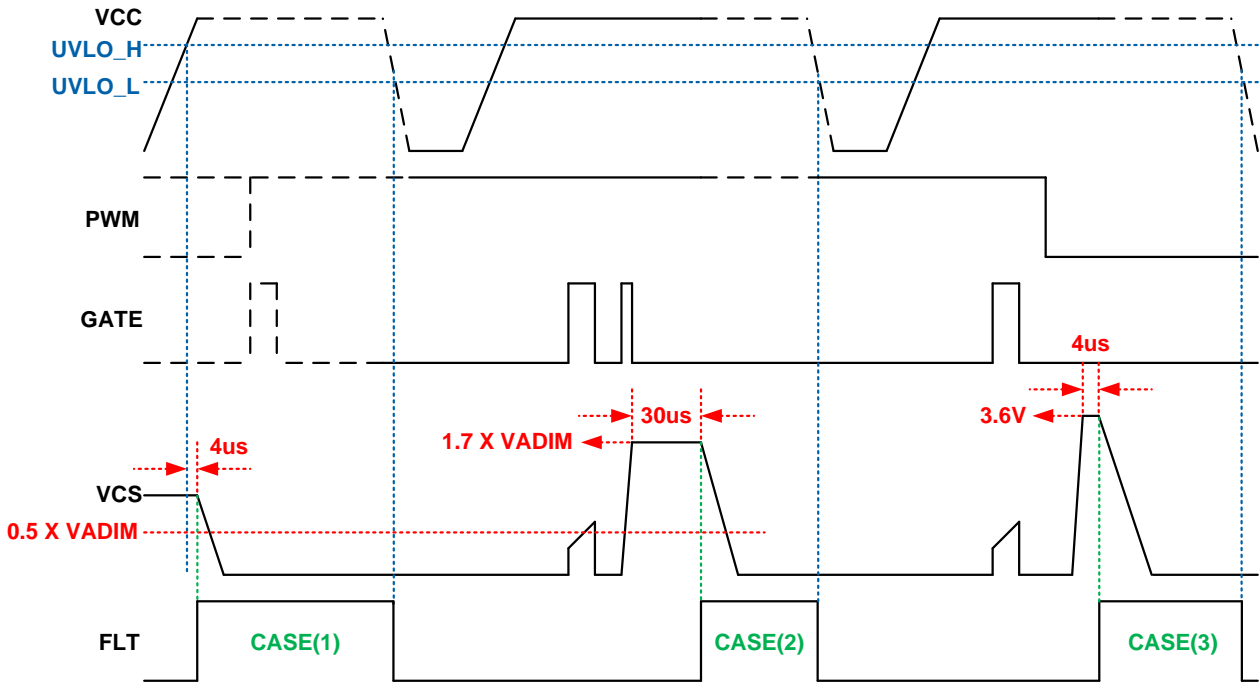
If the CS voltage rises  $V_{SCP}$  during normal operation, the MAP3511 turns-off the GATE output after  $t_{DELAY}$ (typ. 300ns) time. The auto-restart time is typ. 1ms( $t_{RESTART}$ ). This protects for hard instantaneous short such as catch diode, inductor or LED bar short.



### MOSFET D-S Short Detection & FLT Output

In case the following drain-source short events of external MOSFET occur, the FLT pin goes to logic HIGH state immediately. This shuts off the whole system power supply. The protection status is latched and can be cleared by applying a complete power-on-reset(POR).

- CASE(1) : At start-up - Regardless of PWM logic state, if VCS is equal or over than  $0.5 \times VADIM$  and last over 4us. FLT pin voltage goes HIGH level before the first GATE output if PWM is logic HIGH state.
- CASE(2) : At dimming(PWM=logic HIGH) - At first, SCP will be occurred. Even though the GATE is off-state by SCP, if the CS voltage is equal or over than  $0.5 \times VADIM$  and last over 30us.
- CASE(3) : At other condition(PWM=logic LOW) - If the CS voltage is equal or over than 3.6V and lasts over 4us.



The FLT pin is at logic low state when no error is detected.

10

## External Components Selection

### Inductor

In order to achieve accurate constant current output, the MAP3511 is required to operate in Continuous Conduction Mode (CCM) under all operating conditions. In general, the magnitude of the inductor ripple current should be kept as small as possible. If the PCB size is not limited, higher inductance values result in better accuracy of the output current. However, in order to minimize the physical size of the circuit, an inductor with minimum physical outline should be selected such that the converter always operates in CCM and the peak inductor current does not exceed the saturation current limit of the inductor.

The Min. inductance (boundary inductance) which guarantees CCM operation can be calculated as;

$$\Delta I_{LB} = 2 I_{OUT}$$

$$L_{MIN} = \frac{V_{OUT}}{\Delta I_{LB}} \times t_{OFF} = \frac{V_{OUT} \times (1 - D)}{2 \times I_{OUT} \times f_{SW}}$$

The ripple current through chosen inductor is as following equation;

$$\Delta I_L = \frac{(V_{IN} - V_{OUT}) \times D}{L \times f_{SW}}$$

For example, in case  $V_{IN}=175V$ ,  $V_{OUT}=135V$ ,  $I_{OUT}(I_{LED})=425mA$ ,  $f_{SW}=50kHz$  and target ripple current=300mA;

$$D = \frac{V_{OUT}}{V_{IN}} = \frac{135}{175} = 0.77$$

$$L_{MIN} = \frac{V_{OUT} \times (1 - D)}{2 \times I_{OUT} \times f_{SW}} = \frac{135 \times (1 - 0.77)}{2 \times 0.425 \times 50 \times 10^3} = 0.73 [mH]$$

The ripple current at  $L_{MIN}$  is  $2 \times I_{OUT}=850[mA]$  and this is too large to use.

For target ripple current ( $\Delta I_L=300mA$ );

$$L = \frac{(V_{IN} - V_{OUT}) \times D}{\Delta I_L \times f_{SW}} = \frac{(175 - 135) \times 0.77}{0.3 \times 50 \times 10^3} = 2.05 [mH]$$

In this case, the chosen conventional inductor is 2mH/1A.

### MOSFET

The power MOSFET is chosen based on maximum stress voltage, maximum peak MOSFET current, total power losses, maximum allowed operating temperature and the driver capability of the MAP3511.

Maximum stress voltage on the power MOSFET (drain-source voltage) for this buck converter is equal to the input voltage. The power MOSFET must be selected with some voltage margin. For example, if the input voltage is maximally 400 V, then maximum drain-source voltage should be 450 V or higher.

Maximum peak MOSFET current was selected in order to calculate the inductor size. Also in this case, the power MOSFET must be chosen with some current margin.

The power losses in the MOSFET can be separated into conduction losses and switching losses. The conduction loss,  $P_{COND}$ , is the I<sup>2</sup>R loss across the MOSFET. The conduction loss is given by;

$$P_{COND} = R_{DS(ON)} \times I_{RMS}^2 \times k$$

Where, k is the temperature coefficient of the MOSFET.

The switching loss is related to  $Q_{GD}$  and  $Q_{GS1}$  which determine the commutation time.  $Q_{GS1}$  is the charge between the threshold voltage and the plateau voltage when a driver charges the gate, which can be read in the chart of  $V_{GS}$  vs.  $Q_G$  of the MOSFET datasheet.  $Q_{GD}$  is the charge during the plateau voltage. These two parameters are needed to estimate the turn on and turn off loss.

$$P_{SW} = \frac{Q_{GS1} \times R_G}{V_{DR} - V_{TH}} \times V_{DS} \times I_{IN} \times f_{SW} + \frac{Q_{GD} \times R_G}{V_{DR} - V_{PLT}} \times V_{DS} \times I_{IN} \times f_{SW}$$

where  $V_{TH}$  is the threshold voltage,  $V_{PLT}$  is the plateau voltage,  $R_G$  is the gate resistance,  $V_{DS}$  is the drain-source voltage,  $V_{DR}$  is the drive voltage

The total gate charge,  $Q_G$ , is used to calculate the gate drive loss. The expression is

$$P_{DR} = Q_G \times V_{DR} \times f_{SW}$$

Fast switching MOSFETs can cause noise spikes which may affect performance. To reduce these spikes a drive resistor can be placed between GATE pin and the MOSFET gate.

### Catch Diode

The catch diode is chosen based on its maximum stress voltage, its maximum peak current and total power losses. The power losses are lower for a larger duty cycle and vice-versa, because the diode is opened (connected) during off-time.

Maximum voltage stress across the diode is equal to the input voltage  $V_{IN}$ , and therefore the power diode must be selected with some voltage margin. For example, if the input voltage is maximally 400 V, then maximum repetitive peak reverse voltage ( $V_{RRM}$ ) should be 450 V or higher.

Maximum peak diode current is selected in order to calculate the inductor size. Also in this case, the catch diode must be selected with some current margin.

The voltage drop across the diode in a conducting state is primarily responsible for the losses in the diode. The power dissipated by the diode can be calculated as the product of the forward voltage and the output load current for the time that the diode is conducting. The switching losses which occur at the transitions from conducting to non-conducting states are very small compared to conduction losses and are usually ignored. The power dissipated by the catch diode is given by:

$$P_D = V_D \times I_o \times (1 - D)$$

Where,  $V_D$  is the forward voltage drop of the catch diode.

### Input Capacitor

Select the input capacitor to ensure that the input voltage ripple is within a desired range (1% to 5% of the input bus voltage). The input capacitor is usually electrolytic and its ESR dominates its impedance.

A 4.7 $\mu$ F to 22 $\mu$ F electrolytic capacitor will usually suffice.

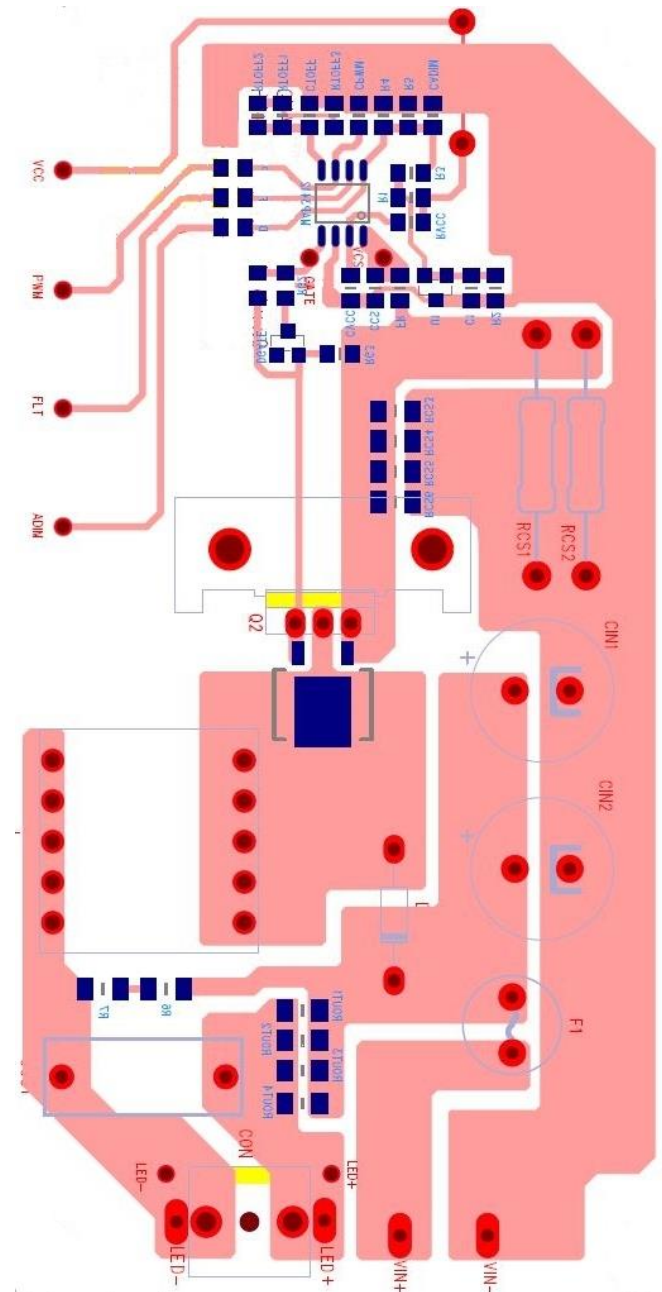
### Output Capacitor

Selecting a suitable capacitor can reduce LED current ripple and increase LED life-time. Note that having too large of a capacitance will cause the LED current to respond slowly. The typical value of the capacitor is 0.33 $\mu$ F.

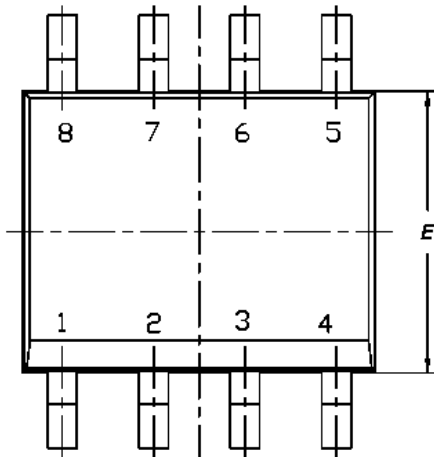
### PCB LAYOUT GUIDE

A gate drive signal output from GATE pin becomes noise source, which may cause malfunction of IC due to cross talk if placed by the side of an analog line. It is recommended to avoid placing the output line especially by the side of CS, ADIM and TOFF pins as far as possible.

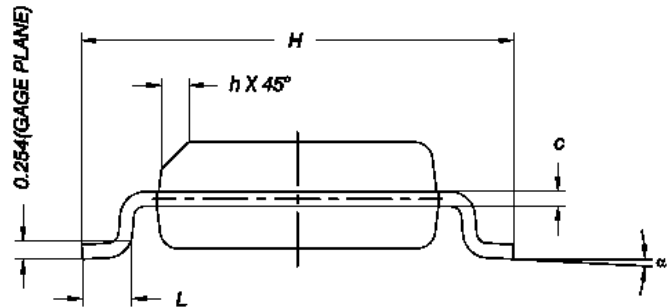
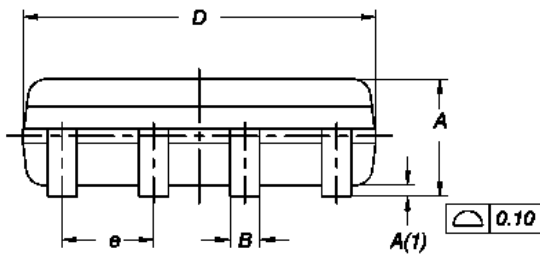
Following figure shows an example of demo board.



**Physical Dimensions**



DIM.	MILLIMETERS		
	MIN.	NOM.	MAX.
A	1.35	1.55	1.75
A(1)	0.10	0.175	0.25
B	0.38	0.445	0.51
C	0.19	0.22	0.25
D	4.80	4.90	5.00
E	3.80	3.90	4.00
e	1.27 BSC		
H	5.80	6.00	6.20
L	0.50	0.715	0.93
$\alpha$	0°	4°	8°
h	0.25	0.375	0.50



**8 Leads SOIC**

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**MagnaChip Semiconductor Ltd.**

891, Daechi-Dong, Kangnam-Gu, Seoul, 135-738 Korea

Tel : 82-2-6903-3451 / Fax : 82-2-6903-3668 ~9

[www.magnachip.com](http://www.magnachip.com)

### Datasheet Revision History

Date	Version	Changes
2014-12-12	Version 1.0	Initial release