

RT9229 Data Sheet



Advanced Dual PWM and Dual Linear Power Controller

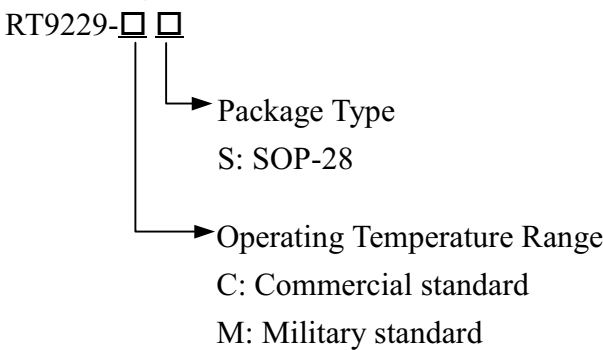
General Description

The RT9229 is a 4-in-one power controller optimized for high-performance microprocessor and computer applications. The IC integrates two PWM controllers, a linear regulator and a linear controller as well as monitoring and protection functions into a 28-pin SOP package. The first PWM controller regulates the microprocessor core voltage with a synchronous buck converter, while the second PWM controller supplies the 3.3V power with a standard buck converter. The linear regulator provides power for the clock driver circuit and the linear controller regulates power for the GTL bus.

The RT9229 features an Intel-compatible, TTL 5-bit programmable DAC that adjusts the core voltage from 2.1V to 3.5V in 0.1V increments and from 1.3V to 2.05V in 0.05V steps. The second PWM controller is user-adjustable for output level between 3.0V and 3.5V with $\pm 2.5\%$ accuracy. The 5-bit DAC has a typical $\pm 1\%$ tolerance. The linear regulator uses an internal drive device to provide 2.5V $\pm 2.5\%$ output voltage. The linear controller drives an external N-channel MOSFET or a low cost NPN bipolar transistor to provide 1.5V $\pm 2.5\%$.

The RT9229 monitors all the output voltages. A Power-good signal is issued when the core voltage is within $\pm 10\%$ of the DAC setting and the other levels are above their under-voltage levels. Additional build-in over-voltage protection for the core output uses the lower MOSFET to prevent output voltage above 115% of the DAC setting. The PWM over-current function monitors the output current using the voltage drop across the upper MOSFET's $R_{DS(ON)}$, which eliminates the need for a current sensing resistor.

Ordering Information



Features

- 4-in-one Regulated Voltages for Microprocessor Core, I/O, Clock, and GTL
- Compatible with HIP6019B
- Power-Good Output Voltage Monitor

Switching section

- 5-bit DAC Programmable from 1.3V to 3.5V
- $\pm 1\%$ DAC Accuracy
- Fast Transient Response
- Full 0% to 100% Duty Cycle Driver
- Switching Frequency from 50kHz to 500kHz
- Adaptive Non-overlapping Gate Driver
- Over-current Monitor Uses MOSFET $R_{ds(on)}$
- Over-voltage Protection Uses Lower MOSFET

Linear Section

- User-adjustable Linear Regulator Output Voltage
- MOSFET or NPN Driving Capability
- Ultra Fast Response Speed
- Under-voltage Protection
- Internal Thermal Shutdown

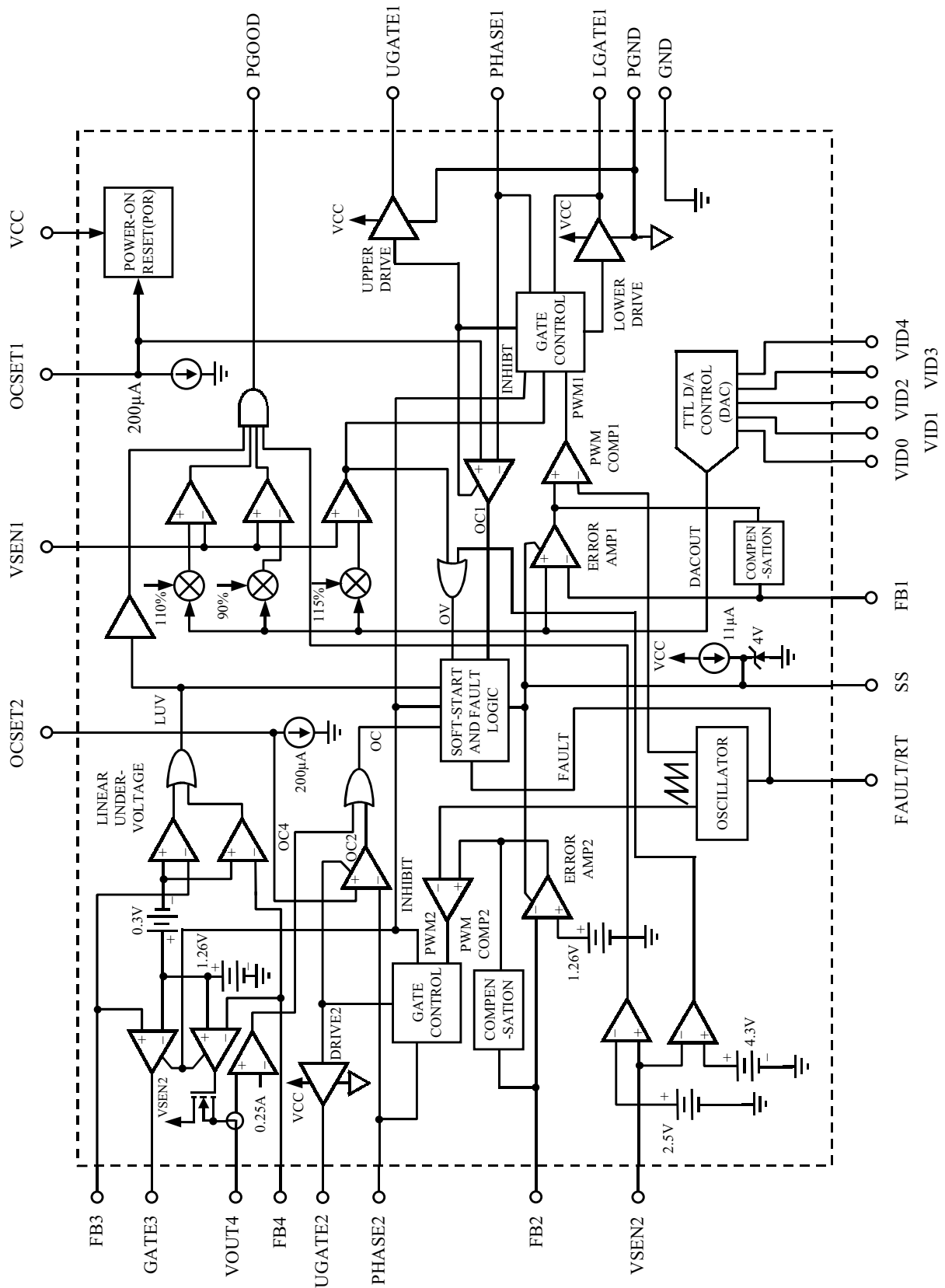
Applications

- Full Motherboard Power Regulation for Computer
- Low-Voltage Distributed Power Supplies

Pin Configurations

Part Number	Pin Configurations
RT9229CS	
	UGATE2 □ 1 28 □ VCC PHASE2 □ 2 27 □ UGATE1 VID4 □ 3 26 □ PHASE1 VID3 □ 4 25 □ LGATE1 VID2 □ 5 24 □ PGND VID1 □ 6 23 □ OCSET1 VID0 □ 7 22 □ VSEN1 PGOOD □ 8 21 □ FB1 OCSET2 □ 9 20 □ NC1 FB2 □ 10 19 □ FB3 NC2 □ 11 18 □ GATE3 SS □ 12 17 □ GND FAULT/RT □ 13 16 □ VOUT4 FB4 □ 14 15 □ VSEN2

Block Diagram



Absolute Maximum Ratings

- Supply Voltage, V_{CC} ----- +15V
- PGOOD, FAULT/RT and GATE Voltage ----- $GND-0.3V$ to $V_{CC}+0.3V$
- Input, Output or I/O Voltage ----- $GND-0.3V$ to 7V
- Ambient Temperature Range (T_A) ----- $0^{\circ}C$ to $+70^{\circ}C$
- Junction Temperature Range (T_J) ----- $0^{\circ}C$ to $+125^{\circ}C$
- Storage Temperature Range (T_{STG}) ----- $-65^{\circ}C$ to $+150^{\circ}C$
- Lead Temperature (Soldering) 10 seconds (T_L) ----- $300^{\circ}C$
- Thermal Impedance Junction to Ambient (θ_{JA}) ----- $75^{\circ}C/W$
- Thermal Impedance Junction to Case (θ_{JC}) ----- $25^{\circ}C/W$

Recommended Operating Conditions

- Supply Voltage, V_{CC} ----- $+12V \pm 10\%$
- Ambient Temperature Range ----- $0^{\circ}C$ to $70^{\circ}C$
- Junction Temperature Range ----- $0^{\circ}C$ to $125^{\circ}C$

CAUTION:

Stresses beyond the ratings specified in “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.

Electrical Specifications

$V_{CC}=12V$, $PGND=0V$, $T_A=25^{\circ}C$, Unless otherwise specified.

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNITS
VCC SUPPLY CURRENT						
Nominal Supply Current	I_{CC}	UGATE1, GATE2, GATE3, LGATE1, and VOUT4 Open	-	10	-	mA
POWER-ON RESET						
Rising VCC Threshold		$V_{OCSET} = 4.5V$	7.5	-	9.5	V
Falling VCC Threshold		$V_{OCSET} = 4.5V$	7	-	9	V
Rising V_{OCSET1} (and 2) Threshold			-	1.25	-	V

OSCILLATOR						
Free Running Frequency		RT = Ooen	180	200	225	kHz
Ramp Amplitude	ΔV_{OSC}	RT = Open	-	1.9	-	V _{p-p}
REFERNECE and DAC						
DAC(VID0-VID4)Input Low Voltage			-	-	0.8	V
DAC(VID0-VID4)Input High Voltage			2.0	-	-	V
DACOUT Voltage Accuracy		DACOUT= 2.05~3.50V	-1	-	1	%
DACOUT Voltage Accuracy		DACOUT =1.30~2.00V	-1%	-	20mV	-
Reference Voltage (Pin FB2 and FB3)			1.240	1.265	1.290	V
LINEAR REGULATOR						
Regulation		10mA<I _{VOUT2} <150mA	-2.5	-	2.5	%
Under-Voltage Level	FB4 _{UV}	FB4 Rising	-	75	87	%
Under-Voltage Hysteresis			-	100	-	mV
Over-Current Protection			180	230	-	mA
Over-Current Protection During Start-Up			-	700	-	mA
LINEAR CONTROLLER						
Regulation		VSEN3= GATE3, 0<I _{GATE3} <20mA	-2.5	-	2.5	%
Under-Voltage Level	FB3 _{UV}	FB3 Rising	-	75	87	%
Under-Voltage Hysteresis			-	100	-	mV
Output Drive Current	I _{GATE3}	VIN2-VOUT3>1.5V	20	40	-	mA
PWM CONTROLLER ERROR AMPLIFIER						
DC Gain			-	65	-	dB
PWN CONTROLLER GATE DRIVER						
Upper Drive1 (and 2) Source	R _{UGATE}	VCC=12V, VCC-V _{UGATE} =1V	-	3	7	Ω
Upper Drive1 (and 2) Sink	R _{UGATE}	V _{UGATE} =1V	-	3	7	Ω
Lower Drive Source	I _{LGATE1}	VCC=12V, V _{LGATE1} =2V	-	1	-	A
Lower Drive Sink	R _{LGATE1}	V _{LGATE1} =1V	-	2	6	Ω
PROTECTION						
V _{OUT1} Over-voltage Trip		VSEN1 Rising	112	115	118	%
V _{OUT2} Over-voltage Trip		VSEN2 Rising	4.1	4.3	4.5	V
FAULT Souring Current	I _{OVF}	V _{FAULT} =8V	10	14	-	mA
OCSET1 (and 2) Current Source	I _{OCSET}	V _{OCSET} =4.5V _{DC}	170	200	230	μ A
Soft-Start Current	I _{SS}	V _{SS} =1V	-	11	-	μ A
POWER GOOD						
V _{OUT1} Upper Threshold		VSEN1 Rising	108	-	112	%
V _{OUT1} Under Voltage		VSEN1 Rising	90	-	94	%
V _{OUT1} Hysteresis(VSEN1/DACOUT)		Upper/Lower Threshold	-	2	-	%
PGOOD Voltage Low	V _{PGOOD}	I _{PGOOD} =-4mA	-	-	0.5	V

Functional Pin Description**VSEN1, VSEN2 (Pins 22 and 15)**

These pins are connected to the PWM converters' output voltage. The PGOOD and OVP comparator circuits use these signals to report output voltage status and for over-voltage protection. VSEN2 provides the input power to the integrated linear regulator.

OCSET1, OCSET2 (Pins 23 and 9)

Connect a resistor (R_{OCSET}) from this pin to the drain of the upper MOSFET. R_{OCSET} , an internal 200 μ A current source (I_{OCSET}), and the upper MOSFET on-resistance ($r_{DS(ON)}$) set the converter over-current (OC) trip point according to the following equation:

$$I_{PEAK} = \frac{I_{OCSET} \times R_{OCSET}}{r_{DS(ON)}}$$

An over-current trip cycles the soft-start function. Sustaining an over-current for 2 soft-start intervals shuts down the controller.

SS (Pin 12)

Connect a capacitor from this pin to ground. This capacitor, along with an internal 11 μ A ($V_{SS} > 1V$) current source, sets the soft-start interval of the converter.

Pulling this pin low with an open drain signal will shut down the IC.

VID0, VID1, VID2, VID3, VID4 (Pin 7, 6, 5, 4, and 3)

VID0~4 are the input pins to the 5-bit DAC. The states of these five pins program the internal voltage reference, DACOUT. The level of DACOUT sets the core converter output voltage (V_{OUT1}). It also sets the core PGOOD and OVP thresholds. Table 1 specifies the DACOUT voltage of 32 combinations of VID levels.

FB1, FB2 (21 and 10)

FB1, 2 are the available external pins of the PWM error amplifiers. Both the FB pins are the inverting input of the error amplifiers.

PGOOD (Pin 8)

PGOOD is an open collector output used to indicate the status of the PWM converter output voltage. This pin is pulled low when the core output is not within $\pm 10\%$ of the DACOUT reference voltage, or when any of the other outputs are below their under-voltage thresholds. The PGOOD output is open for '11111' VID code. See table 1.

PHASE1, PHASE2 (Pins 26 and 2)

Connect the PHASE pins to the PWM converter's upper MOSFET source. These pins are used to monitor the voltage drop across the upper MOSFETs for over-current protection.

UGATE1, UGATE2 (Pins 27 and 1)

Connect UGATE pins to the respective PWM converter's upper MOSFET gate. This pin provides the gate drive for the upper MOSFETs.

PGND (Pin 24)

This is the power ground of UGATE1, LGATE1, and UGATE2. Tie the synchronous PWM converter's lower MOSFET source to this pin.

LGATE1 (Pin 25)

Connect LGATE1 to the synchronous PWM converter's lower MOSFET gate. This pin provides the gate drive for the lower MOSFET.

VCC (Pin 28)

Provide a 12V bias supply for the IC to this pin. This pin also provides the gate bias charge for all the MOSFETs controlled by the IC.

FAULT/RT (Pin 13)

This pin provides oscillator switching frequency adjustment. By placing a resistor (R_T) from this pin to GND, the nominal 200kHz switching frequency is increased according to the following equation:

$$F_s = 200\text{kHz} + \frac{3.5 \times 10^6}{R_T(\text{k}\Omega)} (R_T \text{ to GND})$$

Conversely, connecting a pull-up resistor (R_T) from this pin to VCC reduces the switching frequency according to the following equation:

$$F_s = 200\text{kHz} - \frac{2.8 \times 10^7}{R_T(\text{k}\Omega)} (R_T \text{ to } 12V)$$

Nominally, this pin voltage is 1.26V, but is pulled to VCC in the event of an over-voltage or over-current condition.

GATE3 (Pin 18)

Connect this pin to the gate of an external MOSFET or the base of a NPN. This pin provides the drive for the linear controller's pass transistor.

FB3 (Pin 19)

Connect this pin to a resistor divider to set the linear controller output voltage.

FB4 (Pin 14)

Connect this pin to a resistor divider to set the linear regulator output.

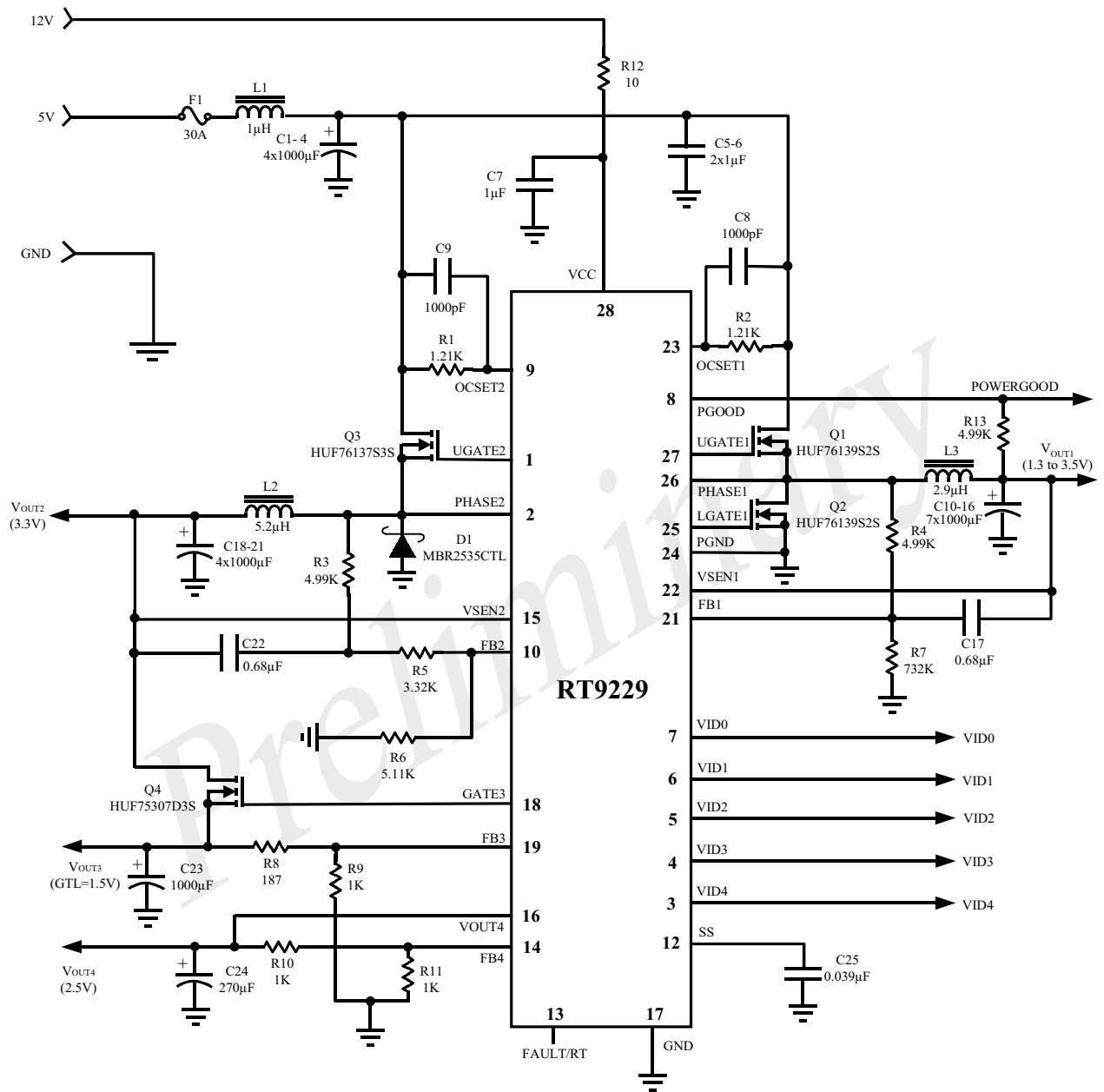
VOUT4 (Pin 16)

Output of the linear regulator. Supplies current up to 230mA.

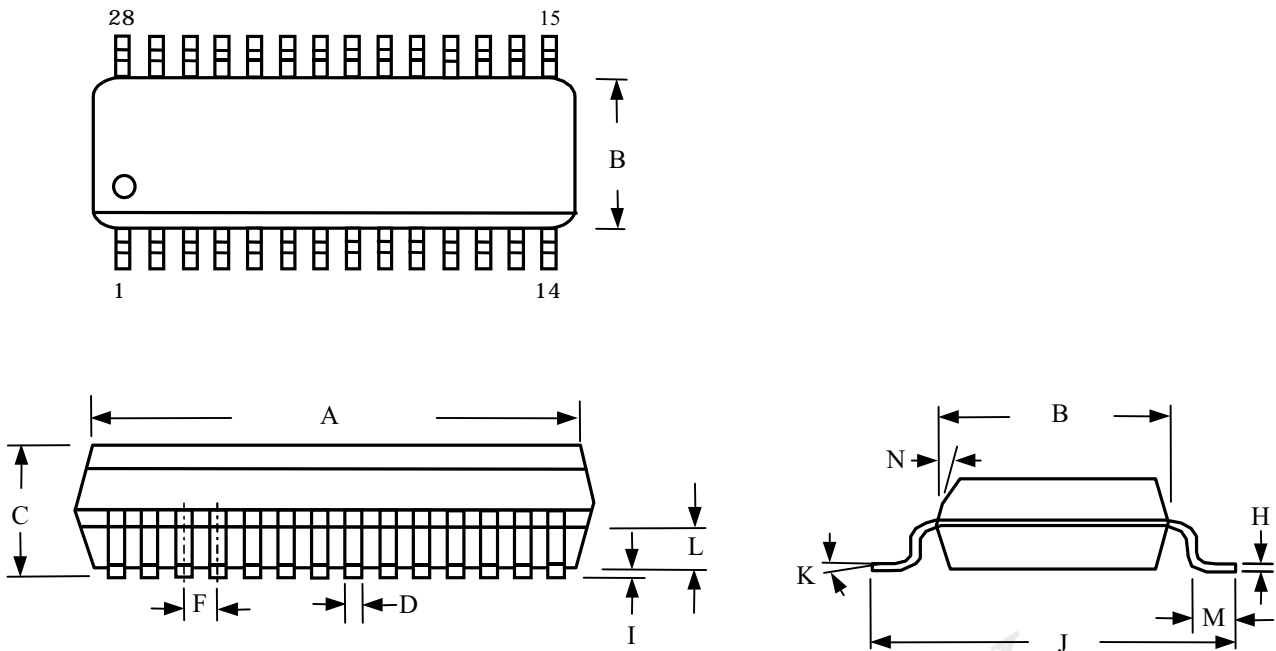
Table 1. VOUT1 Voltage Program

Pin Name					Normal OUT1 Voltage DACOUT
VID4	VID3	VID2	VID1	VID0	
0	1	1	1	1	1.30
0	1	1	1	0	1.35
0	1	1	0	1	1.40
0	1	1	0	0	1.45
0	1	0	1	1	1.50
0	1	0	1	0	1.55
0	1	0	0	1	1.60
0	1	0	0	0	1.65
0	0	1	1	1	1.70
0	0	1	1	0	1.75
0	0	1	0	1	1.80
0	0	1	0	0	1.85
0	0	0	1	1	1.90
0	0	0	1	0	1.95
0	0	0	0	1	2.00
0	0	0	0	0	2.05
1	1	1	1	1	INHIBIT
1	1	1	1	0	2.10
1	1	1	0	1	2.20
1	1	1	0	0	2.30
1	1	0	1	1	2.40
1	1	0	1	0	2.50
1	1	0	0	1	2.60
1	1	0	0	0	2.70
1	0	1	1	1	2.80
1	0	1	1	0	2.90
1	0	1	0	1	3.00
1	0	1	0	0	3.10
1	0	0	1	1	3.30
1	0	0	1	0	3.30
1	0	0	0	1	3.40
1	0	0	0	0	3.50

Typical Application Circuit



Package Information



Symbols	Dimensions In Inches			Dimensions In Millimeter		
	Min	Norm	Max	Min	Norm	Max
A	0.701	0.705	0.709	17.800	17.900	18.000
B	0.291	0.295	0.299	7.400	7.500	7.600
C	0.090	0.092	0.094	2.280	2.330	2.380
D	0.015	0.016	0.017	0.390	0.400	0.410
F	-	0.050	-	-	1.270	-
H	0.008	0.009	0.010	0.200	0.230	0.260
I	0.003	0.006	0.009	0.080	0.160	0.240
J	0.405	0.409	0.413	10.300	10.400	10.500
K	-	5°	-	-	5°	-
L	0.035	0.039	0.043	0.900	1.000	1.100
M	0.020	0.028	0.035	0.500	0.700	0.900
N	--	7°	--	--	7°	--